

Q o g s

Prerequisites

There are no formal prerequisites, as all students are expected to have attended the Part II Thermal & Statistical Physics course (or equivalent, for the MAST cohort). It would be helpful to have attended the Part II Soft Condensed Matter option; for those who have not, the lectures cover the essential material.

Learning Outcomes and Assessment

This is a theoretical course that focuses on the microscopic processes that drive fluctuations, examining the fundamentals and modern techniques of statistical mechanics, with applications in non-equilibrium thermal physics, diffusion and viscoelasticity, genetics and evolution, and stock markets. However, the in-depth topics are all “physical”, covering the mean first-passage time, non-Markov noise and anomalous diffusion, and the crossover between quantum and statistical uncertainty.

Synopsis

o l a r f l : Equilibrium statistical mechanics revised via partition functions / free energy, and via rates / detailed balance.

l e p f m l p p p Markov process, Poisson and Wiener processes, Stochastic differential equations; conversion from Langevin to Fokker-Planck and Smoluchowski equations; Example 1 – Black-Scholes equation for the price of stocks. Detailed balance; Correlation functions; Fluctuation-dissipation theorem.

m m f f l p l c I d s f a v j f p Diffusion in shear flow. Example 2 – viscosity of a simple fluid. Ornstein-Uhlenbeck theory; Diffusion in external potentials; Periodic and random potentials; Kramers escape theory and mean first-passage time. Example 3 – “hitting a small target”.

o i f p a I d s f a v j f p Covariant formulation of multi-variable stochastic processes; Fokker-Planck and Smoluchowski equations; Non-Markov stochastic process, viscoelasticity and memory functions; Generalised (viscoelastic) Langevin equation and anomalous diffusion; Dissipation as coupling to an ensemble of oscillators; Mori equation; Liouville equation for dynamical variable and for distribution function (Heisenberg and Schrodinger formalisms). Example 4 – Kubo formula.

r r j o l p l s o Quantum and stochastic probabilities; statistics of the density matrix; Dissipation as coupling to an ensemble of oscillators. Example 5 – Marcus equation for electron transfer. Example 6 – rate of escape over and tunnelling under the potential barrier

KEY BOOKS

Nonequilibrium Statistical Mechanics, Zwanzig R. (OUP 2001)

Introduction to Stochastic Processes, 2nd Edition, Lawler G. F. (Chapman & Hall 2006)

Brownian Motion: Fluctuations, Dynamics, and Applications, Mazo R. (OUP 2002)

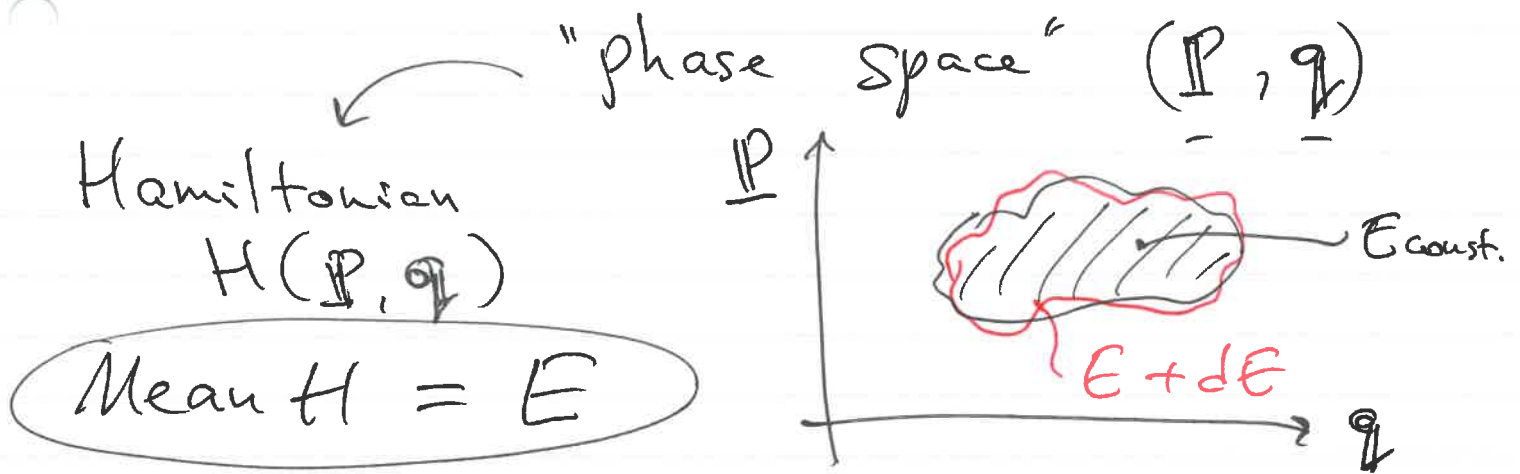
Fokker-Planck Equation, Risken H. (Springer 1996)

Advanced Statistical Mechanics (2024)

Lecture 1

Brief recap of
"Statistical physics"

Microcanonical Ensemble



Find area: $\int d\underline{P} d\underline{q}$

$$E < H(\underline{P}, \underline{q}) < E + dE$$

$$= \int \left(\Theta[E + dE - H] - \Theta[E - H] \right) d\underline{P} d\underline{q}$$

Step-functions $\Theta(x)$ ↗

$$= dE \int \frac{d}{dE} \Theta(E - H) d\underline{P} d\underline{q}$$

$$\frac{d}{dx} \Theta(x) = \delta(x)$$

Define: $\Omega(E) = \int \delta(E - H) d\underline{P} d\underline{q}$

$\Omega(E)$ is the number of states
with $H(p, q) = E$ fixed E

Define $S(E) = \ln \Omega(E)$

the entropy of this microstate
(with constant E)

Define probability $P(E)$:

$$\text{Mean } X(p, q) = \int X(p, q) P(E) dE$$

$$= \int X(p, q) \delta(E - H(p, q)) dp dq$$
$$\Omega(E)$$

Hence $P(E) = \frac{\delta(E - H(p, q))}{\Omega(E)}$ of a
state within
the microstate (E)
Normalised!

Easier to

$$\Omega(E) \equiv \int \Omega(E_1) \delta(E - E_1) dE_1$$

Since $\Omega(E)$ is not normalised,
there is an extra $\int \Omega(E) dE$

⊙ Canonical ensemble

of many microstates exchanging energy between

Define $e^{-\beta E}$ "weight"

Define probability — but first: its normalisation factor

$$Z = \sum_{\text{all states}} e^{-\beta E} = \int dP dq e^{-\beta H(p,q)}$$

$(\int dP dq)$ —

re-order this summation: over microstates

$$Z = \sum_{\text{Microstates } (E)} e^{-\beta E} \cdot \Omega(E)$$

$e^{-\beta E} \rightarrow e^{-\beta(E - TS(E))}$

~~$Z = Z$~~

P — microstates

probability: $p(E) = \frac{1}{Z} e^{-\beta(E - TS(E))}$

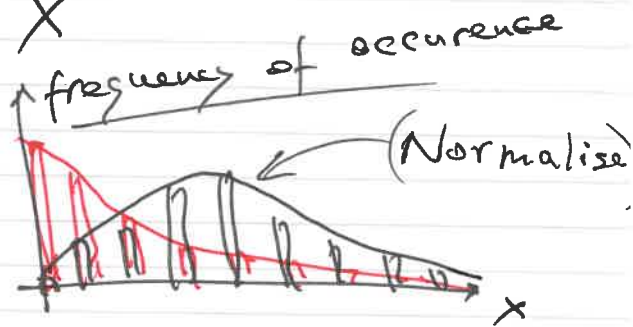
Lecture 2

Basic terms and definitions of probability theory.

⊙ "Random", or "Stochastic" variable: X

Probability $P(x)$:

Such that



$$\langle x \rangle = \int x P(x) dx \quad \int P(x) dx = 1$$

Also $\langle \Delta x^2 \rangle = \langle x^2 \rangle - \langle x \rangle^2 \equiv \sigma^2$
Variance

⊙ Characteristic function (of X)

$$\phi_x(k) \stackrel{\text{def.}}{=} \left\langle e^{ikx} \right\rangle_{P(x)}$$

This is just a FT of $P(x)$:

$$\phi_x(k) = \int e^{ikx} P(x) dx$$

$$= \int \sum_n \frac{1}{n!} (ikx)^n P(x) dx$$

$$= \sum_{n=0}^{\infty} \frac{1}{n!} (ik)^n \langle x^n \rangle$$

← Moments of $P(x)$

Separately, define:

$$\phi_x(k) = \exp \left[\sum_{m=0}^{\infty} \frac{(ik)^m}{m!} C_m \right]$$

So that

cumulants of $P(x)$

$$C_n = \frac{d^n}{d(ik)^n} \phi_x(k)$$

$$n=1 \quad C_1 = \frac{d}{d(ik)} \sum_{h=0}^{\infty} \frac{(ik)^h}{h!} C_h \quad \text{or compare (1)}$$

$$= \frac{d}{d(ik)} \sum_h \frac{1}{h!} (ik)^h \langle x^h \rangle \quad (2)$$

$$= \sum_n n \cdot \frac{(ik)^{n-1}}{n!} \langle x^n \rangle = \langle x' \rangle = \langle x \rangle$$

cancel {n} and renumber the sum in numerator

Check yourself:

If $P(x)$ is Gaussian,

$$\phi_x(k) \text{ is also } P(x) \approx e^{-\frac{(x-x_0)^2}{2\sigma^2}}$$

① If there is a linked sequence of random variables:

$$Y_N = \underline{X_1} + \underline{X_2} + \dots + \underline{X_N}$$

Each of these has same $P(x)$

is called "Random walk"

or
"Stochastic process"

Then: $\langle Y_N \rangle = N \langle x \rangle$

Variance: $\langle \Delta Y_N^2 \rangle = \langle Y_N^2 \rangle - \langle Y_N \rangle^2$

$$= \sum_{i,j} \langle x_i x_j \rangle = \sum_i \langle x_i \rangle \sum_j \langle x_j \rangle$$

$$= \sum_i \langle x_i^2 \rangle + \sum_{i \neq j} \langle x_i x_j \rangle = N \langle x^2 \rangle + N(N-1) \langle x \rangle^2$$

$$= N \langle x^2 \rangle + N(N-1) \langle x \rangle^2 = N \langle x^2 \rangle - N \langle x \rangle^2$$

$$= N (\langle x^2 \rangle - \langle x \rangle^2) = N \sigma^2$$

Central Limit Theorem

Take a "normalised" random walk

$$S_N = \frac{Y_N}{N} \text{ such that } \langle S_N \rangle = \langle x \rangle$$

for large N and Variance = $\frac{\sigma^2}{N}$

$P(S_N)$
converges to
a Gaussian

Proof via
characteristic
function:

$$\begin{aligned} \phi_S(k) &= \langle e^{iks} \rangle_{P(s)} = \langle e^{\frac{ik}{N} \sum_m x_m} \rangle \\ &= \left(e^{\frac{ik}{N} x} \right)^N_{P(x)} \end{aligned}$$

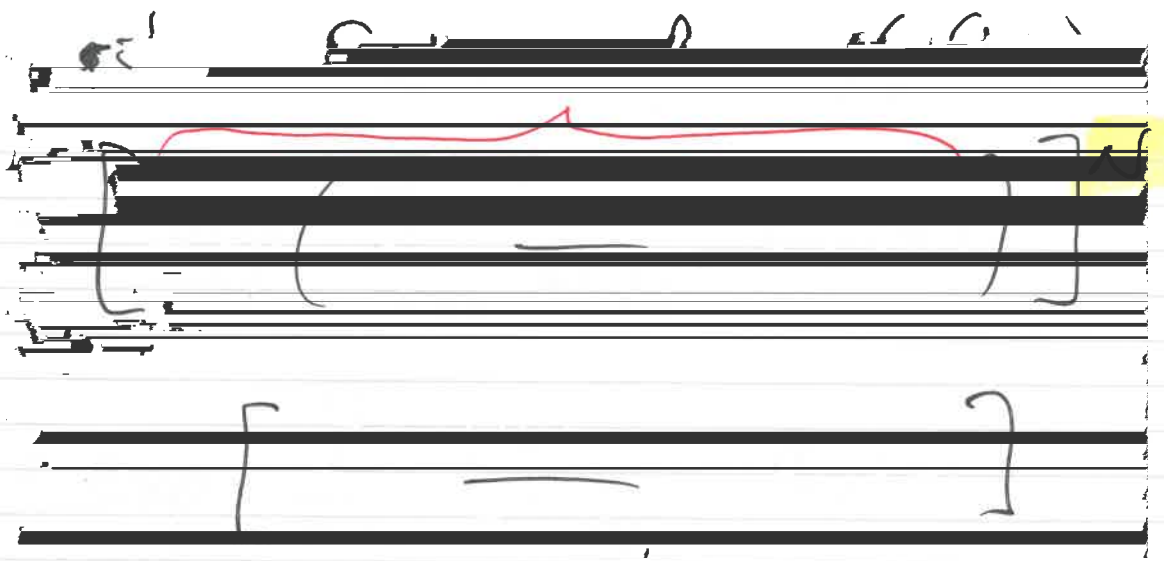
product of N exponentials

But this is the characteristic function $\phi_x(k/N)$ raised to N

Separately:

$$\begin{aligned} \phi_S(k) &= \exp \left[\sum_{m=0}^{\infty} \frac{(ik)^m}{m!} C_m(s) \right] \\ &= \left[\phi_x(k/N) \right]^N \end{aligned}$$

Now,



product of exponentials ...

→ $n=1$ $\exp(ik C_1(x))$

See the added "note" at the end

→ $n=2$ $\exp\left(-\frac{k^2}{2N} C_2(x)\right)$

No need to go further if $N \gg 1, \dots$

this cuts out the range of possible "k" when $|k| > \sqrt{N}$,
this $\exp(-k^2/N) \rightarrow 0$

Then:

$$\phi_S(k) = \exp\left(N + ik C_1(x) - \frac{k^2}{2N} C_2(x)\right)$$

def. \int

(irrelevant of $|k| < \sqrt{N}$)

over the range $|k| < \sqrt{N}$

$$P(s) \approx \int e^{-iks + ik\langle x \rangle} \cdot e^{-\frac{k^2}{2N}\sigma^2} dk$$

$$= \text{const.} \cdot e^{-\frac{(s - \langle x \rangle)^2}{2\sigma^2/N}}$$

Extend range (k) to ∞ , ignoring higher terms

So it is Gaussian with higher terms

$$\langle S \rangle = \langle x \rangle$$

$$\text{var}(S) = \sigma^2/N$$

① Replace N with time t

→ Stochastic process $Y(t)$

(random walk $y_N = \sum_{m=0}^N x_m$)
and stay with continuous $t \dots$

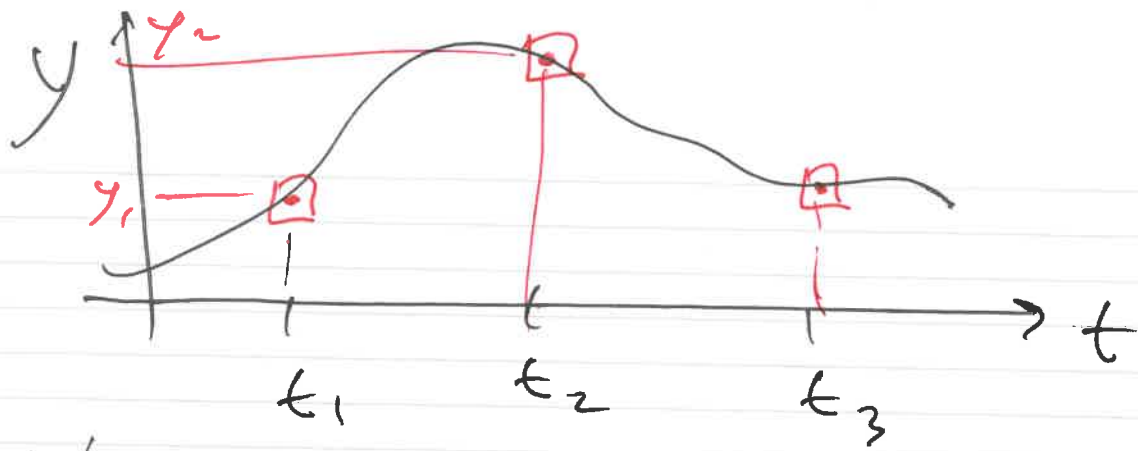
Define set of probabilities:

$P_1(y, t)$: reach value y in t

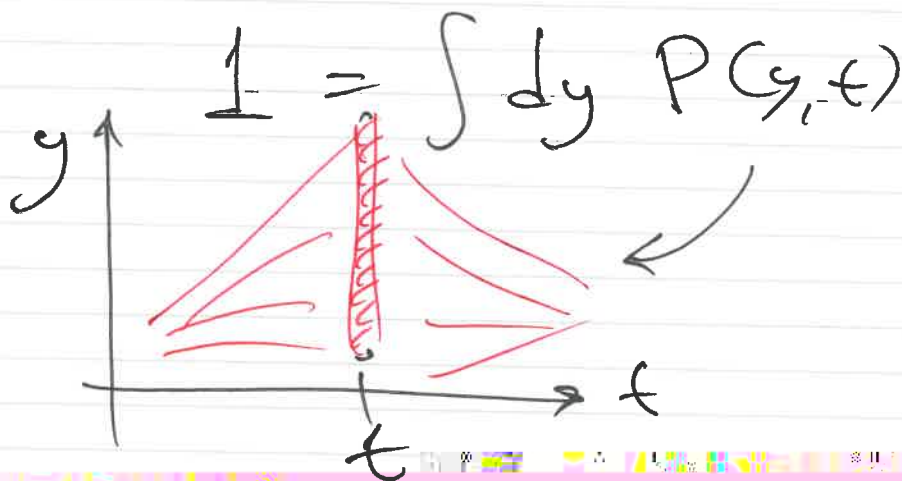
$P_2(y_1, y_2 | t_1, t_2)$:

etc.

(simultaneous)
 y_1 at t_1
and y_2 at t_2



Normalisation:



Also: $1 = \int dy_1 dy_2 \dots P(y_1, y_2, \dots, t_1, t_2, \dots)$

⊙ Reduction:

$$\int dy_N P_N(y_1, y_2, \dots, y_N, \dots) = P_{N-1}(y_1, y_2, \dots, y_{N-1})$$

i.e. $\int dy_2 P_2(y_1, y_2, t_1, t_2) = P_1(y_1, t_1)$

⊙ Correlation function:

$$\langle y(t) \rangle = \int y \cdot P(y, t) dy$$

$$\langle y_1(t_1) y_2(t_2) \rangle = \int dy_1 dy_2 y_1 y_2 P_2(y_1, y_2, t_1, t_2)$$

etc...

○ Stationary process $y(t)$
 is when $P(y, t)$ is
 invariant with time shift

$$t \rightarrow t + \Delta t$$

$\langle y(t) \rangle$ is not t -dependent

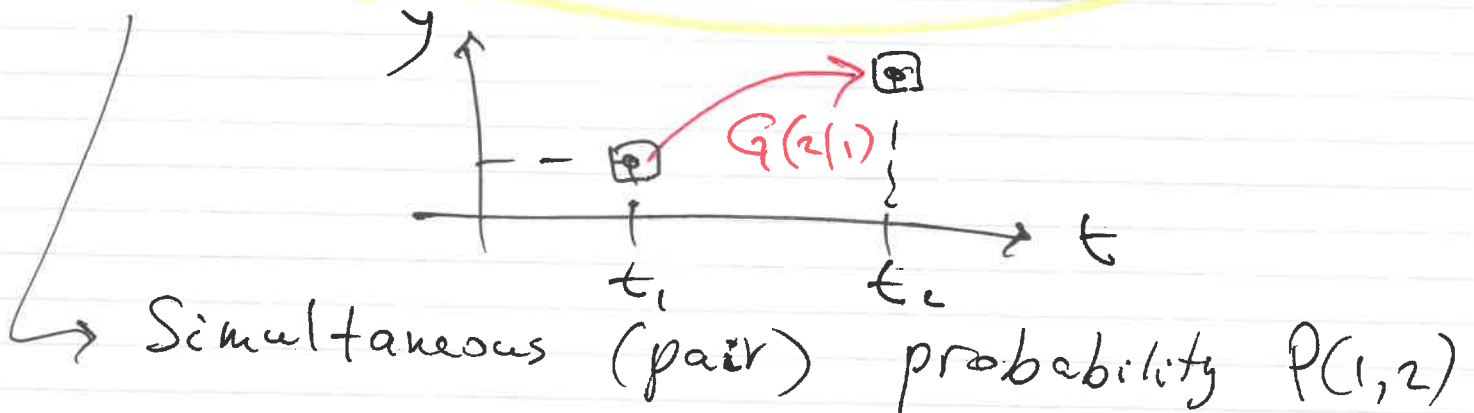
$$\langle y(t_1) y(t_2) \rangle \sim f(t_1 - t_2)$$

etc.

(so that $t_1 + \Delta t$
and $t_2 + \Delta t$)

○ Conditional probability
 = Propagator

$$P_2(y_2 | t_2) = G[2|1] P_1(y_1 | t_1)$$



(1) Markov process (without memory)
 fully determined
 by $P_1(y, t)$ and $G(y_2, y_1 | t_2, t_1)$

(2) Evolution relation

$$P_1(y_2, t_2) = \int G[y_2, y_1 | t_2, t_1] P_1(y_1, t_1) dy_1$$

(3) Kolmogorov Chapman relation

$$\frac{\partial}{\partial t} P(y_2, t_2) = - \int G(y_2, y_1 | t_2, t_1) P(y_1, t_1) dy_1 + \int G(y_1, y_2 | t_2, t_1) P(y_1, t_1) dy_1$$

difference with "Evolution" is that we retain (track) the initial condition $y_1(t_1)$ here

A Note about C.L.T.

We expand in exponent:

$$\phi_S(k) = \left[\phi_x\left(\frac{k}{N}\right) \right]^N$$

$$= \exp \left[1 + (ik) \langle x \rangle - \frac{k^2}{N} c_2(x) \right.$$

$$\left. + \frac{ik^3}{N^2} c_3 + \dots + \frac{k^n}{N^{n-1}} c_n + \dots \right]$$

$$e^{ik \langle x \rangle} \cdot e^{-\frac{k^2}{N} c_2} \cdot e^{\dots} e^{-\frac{k^n}{N^{n-1}} c_n}$$

$$|k| \sim \sqrt{N}$$

$$|k| \sim N^{1-1/N}$$

almost ...
(wider)

$$e^{\frac{k^n}{N^{n-1}} c_n} \approx 1$$

Hence only the k^2 term matters

Gaussian $e^{-\frac{k^2}{2N} c_2}$ is the

last non-trivial term in the

Lecture 3 Stationary Markov process(es)

with the propagator

$$G(y_2, y_1 | t_2 - t_1)$$

Two of these processes are especially important in Physics

Wiener process

independent steps

\pm equal **Must step**

Gaussian step distribution

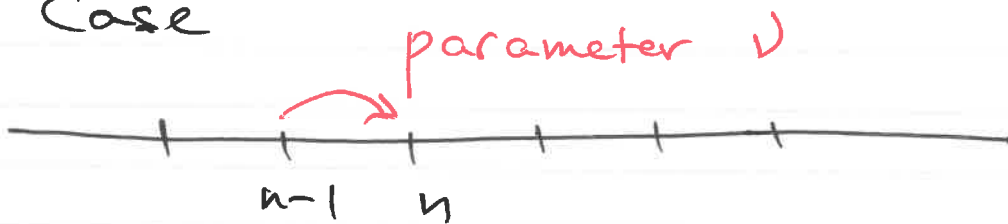
Poisson process

independent steps

only forward or not

"number of hits in a fixed target"

1D case



v : rate of a single step

probability to make a step in time dt

$$p_+ = v dt$$

The whole stochastic process: $n(t)$

if $n(t) = 0$ then $p_+ = 0$

Still within a single step:
(n-1) \rightarrow (n)

① What is the total (cumulative) probability to make this step in time t : $W(t)$

② Or equivalently, what is the "Survival probability" to still not step in time t :

$$S(t) = 1 - W(t)$$

Then:

$$S(t+dt) = S(t) - v dt \cdot S(t)$$

$$\frac{dS}{dt} = -v S$$

$$\text{if } t=0, \\ S(t) = 1$$

$$S(t) = e^{-vt}$$

Now define probability density:

$$w = \frac{\partial W(t)}{\partial t} = -\frac{\partial S(t)}{\partial t} = v e^{-vt}$$

So we can evaluate integrals:

$$\text{Average time} \left. \begin{array}{l} (n-1) \rightarrow (n) \\ \text{step} \end{array} \right\} \langle t \rangle = \int_0^{\infty} t w(t) dt = 1/v$$

Also $\langle t^2 \rangle - \langle t \rangle^2 = 1/v^2$, etc.

Exercise (simulation):

fix time of step Δt , and
"flip a biased coin":

$$p_+ = v \Delta t \quad \text{and} \quad p_0 = 1 - v \Delta t$$

When do we reach a point (k)
after a time $t = N \Delta t$. make k steps

This is a binomial distribution

$$P(k, N) = \frac{N!}{k!(N-k)!} p_+^k p_0^{N-k}$$

to reach (k) after (N) steps

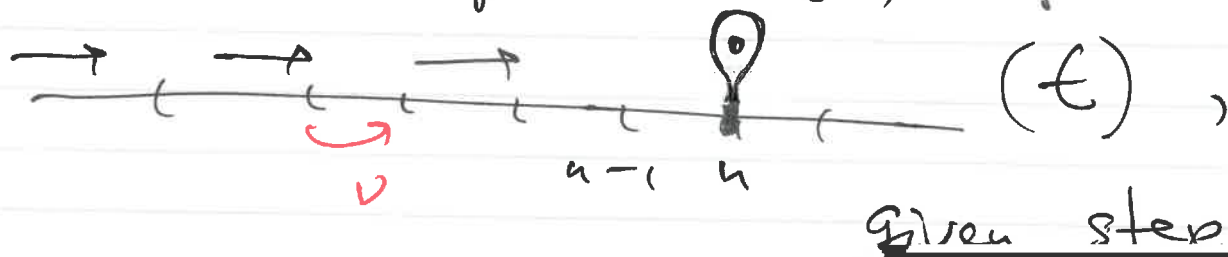
At large N , with Np constant

reduces to

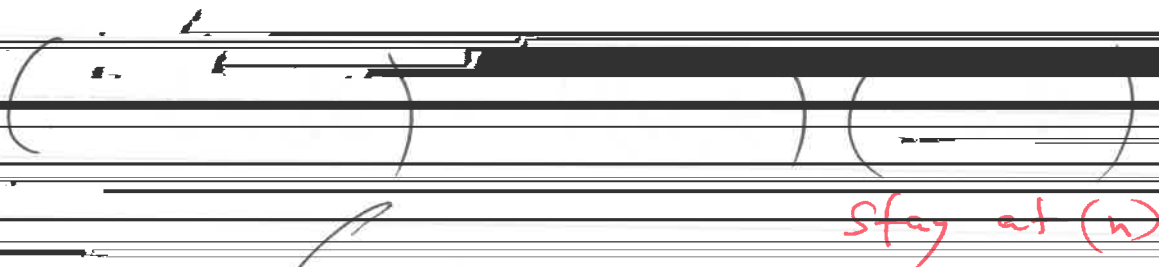
$$p(k, \lambda) = \frac{\lambda^k}{k!} e^{-\lambda} \quad \text{this is "Poisson"}$$

Now let's derive understand it.

- What is the probability to reach a position (n) after time (t) ,



The



step from $(n-1)$

This is often called the "Master Equation"

$$\dot{P} = \text{rate in} - \text{rate out}$$

Recall we saw "characteristic function"

$$\phi_X(k) = \langle e^{ikx} \rangle_{P(x)}$$

Similar logic employs the "generating function"

$$g(k, t) = \sum_{n=0}^{\infty} P(n, t) k^n$$

$$\text{Now: } \frac{\partial g(k,t)}{\partial t} = \sum_{n=0}^{\infty} k^n \cdot \nu [P(n-1,t) - P(n,t)]$$

remember the sum

$$= \sum_{n=0}^{\infty} \nu (k^{n+1} - k^n) P(n,t)$$

$$= \nu \cdot (k-1) \sum_{n=0}^{\infty} k^n P(n,t)$$

but this is the definition

of $g(k,t)$

$$\frac{\partial g}{\partial t} = \nu (k-1) \cdot g$$

At $t=0$

$$P(n,0) = \delta_{n,0}$$

$$g(k,0) = 1$$

$$g(k) = e^{\nu(k-1)t}$$

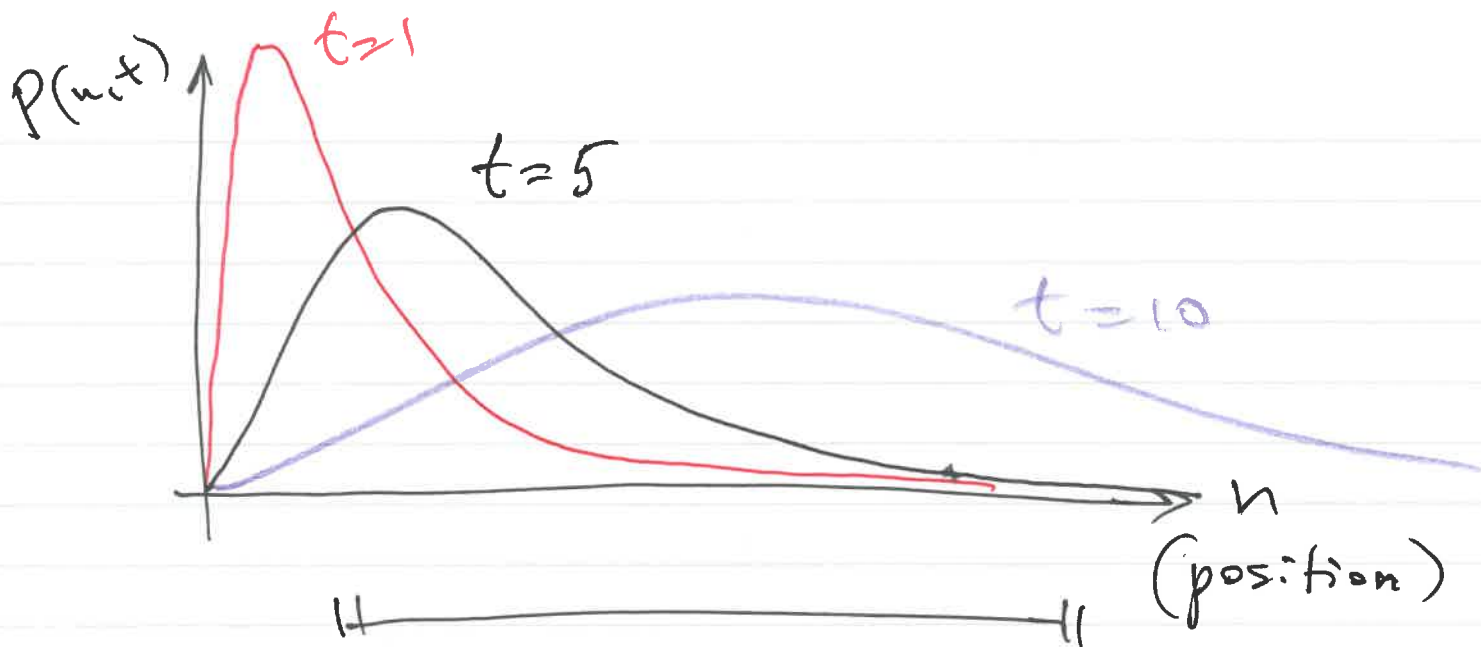
Now expand this exponential:
(to isolate $\sum_n k^n (\dots)$)

$$g(k,t) = e^{-\nu t} \sum_{n=0}^{\infty} \frac{(\nu k t)^n}{n!} = \sum_{n=0}^{\infty} k^n \left(\frac{(\nu t)^n}{n!} e^{-\nu t} \right)$$

this is the Poisson distribution

$$P(n,t) = \frac{1}{n!} (\nu t)^n e^{-\nu t}$$

Before we had $\lambda = \nu p$, now use (νt) as the "time" parameter



⊙ Average time of the 10th step

$$n=10$$

each step is independent!

$$\langle t_{10} \rangle = 10 \langle t_1 \rangle = 10/v$$

⊙ Probability that 10th step ($n=10$) occurs after time t .

$$P(t_{10} > t)$$

or

$$P(n(t) < 10)$$

9 events at t , then step

$$\int_t^{\infty} \frac{(vt)^9}{9!} e^{-vt'} \cdot v dt'$$

(the step #10 occurs: $t' > t$)

Sum of 0 to 9 steps at t :

$$\sum_{n=0}^9 P(n,t)$$

$$= \sum_{n=0}^9 \frac{(vt)^n}{n!} e^{-vt}$$

They better be equal!

A comment about Master Equation

○ Evolution:

$$P(n, t+\Delta t) = \sum_m G(n, t+\Delta t | m, t) P(m, t)$$

Subtract $P(n, t)$ from both sides

$$\frac{\partial P(n, t)}{\partial t} = \frac{1}{\Delta t} \left[\sum_m G(n, t+\Delta t | m, t) P(m, t) - P(n, t) \cdot \sum_m G(m, t+\Delta t | n, t) \right]$$

$$= \sum_m \frac{G(n, t+\Delta t | m, t)}{\Delta t} \cdot P(m, t)$$

"flux in" ($m \rightarrow n$)

$$- \sum_m \frac{G(m, t+\Delta t | n, t)}{\Delta t} \cdot P(n, t)$$

"flux out" ($n \rightarrow m$)

$$\text{So: } \frac{\partial P(n, t)}{\partial t} = \sum_m \left[w_{nm} P(m, t) - w_{mn} P(n, t) \right]$$

transition probabilities....

Not necessary
to have $n > m$

It is so for Poisson process, but the Evolution relation is more general.

Lecture 4 : Wiener process

Random variable
 X : $p(x)$

Stochastic process

$$Y_x \rightarrow Y(t)$$

when independent steps
each have Gaussian
probability

$$W(t)$$

① Increment $\Delta W = W(t+\Delta t) - W(t)$

has

$$P(\Delta W) = \frac{1}{\sqrt{2\pi\Delta t}} e^{-\frac{\Delta W^2}{2\Delta t}}$$

(Normalise it:
variance = Δt)

② Characteristic function of ΔW

$$\phi(k, t) = \langle e^{ik\Delta W} \rangle_{P(\Delta W)}$$

$$= e^{i W_0} \cdot e^{-\frac{1}{2} k^2 (\Delta t - t_0)}$$

if we had a
condition W_0 at $t=t_0$

③ Scaling: $V(t) = \frac{1}{c} W(ct)$ is also a Wiener

Could we find the full probability of the process

$$W(t) : P(W, t) ?$$

Let's start from Evolution eq:

$$\odot P(W+\Delta W, t+\Delta t) = \int G(\Delta W/\Delta t) P(W, t) dW$$

or it could be propagator: ΔW
Kolmogorov-Chapman:

$$P(W+\Delta W, t+\Delta t | W_0, t_0) = G(\Delta W/\Delta t) P(W, t | W_0, t_0)$$

Change variable: $\Delta W = W(t+\Delta t) - W(t)$
from $dW \rightarrow -d(\Delta W)$

$$P(W+\Delta W, t+\Delta t) = \int G(\Delta W/\Delta t) P(W(t+\Delta t) - \Delta W, t) (-) d\Delta W$$

change the limits of integral back

Small: ΔW Taylor expansion

0-order:

$$P(w+\Delta w, t+\Delta t) = \int G(\Delta w/\Delta t) \cdot P(w(t+\Delta t), t)$$

$$1 = \int G \, d\Delta w$$

1st order:

$$- \int G(\Delta w/\Delta t) \cdot \frac{\partial P}{\partial w} \Delta w \, d\Delta w$$

$$\text{Gaussian: } \int w G \, d\Delta w = 0$$

2nd order:

$$+ \int G(\Delta w/\Delta t) \frac{1}{2} \frac{\partial^2 P(w,t)}{\partial w^2} \Delta w^2 \, d\Delta w$$

! variance of G

(+ ... stop)

All together this makes:

$$\frac{P(\dots, t+\Delta t) - P(\dots, t)}{\Delta t} = \frac{1}{2} \frac{(\text{variance})}{\Delta t} \cdot \frac{\partial^2 P}{\partial w^2}$$

Equivalently

$$\frac{\partial P}{\partial t} = D \frac{\partial^2 P}{\partial w^2}$$

$$D = \frac{(\text{variance})}{2 \Delta t}$$

$$\frac{\partial P}{\partial t} = -\text{div } J$$

flux: prob. current $J = -D \frac{\partial P}{\partial w}$

Equations of this nature,
 for full $P(w, t)$, or $\phi_k(w)$,
 are called "kinetic" or
 macroscopic.

On the microscopic level of $w(t)$
 we have "stochastic differential
 equation" (SDE)

(1905 Einstein, Smoluchowski
 → 1911 Langevin equation)

We saw this in ~~Simple~~ Brownian motion:

$$m \frac{dv}{dt} = \sum \text{forces} = -\gamma v + \tau(t)$$

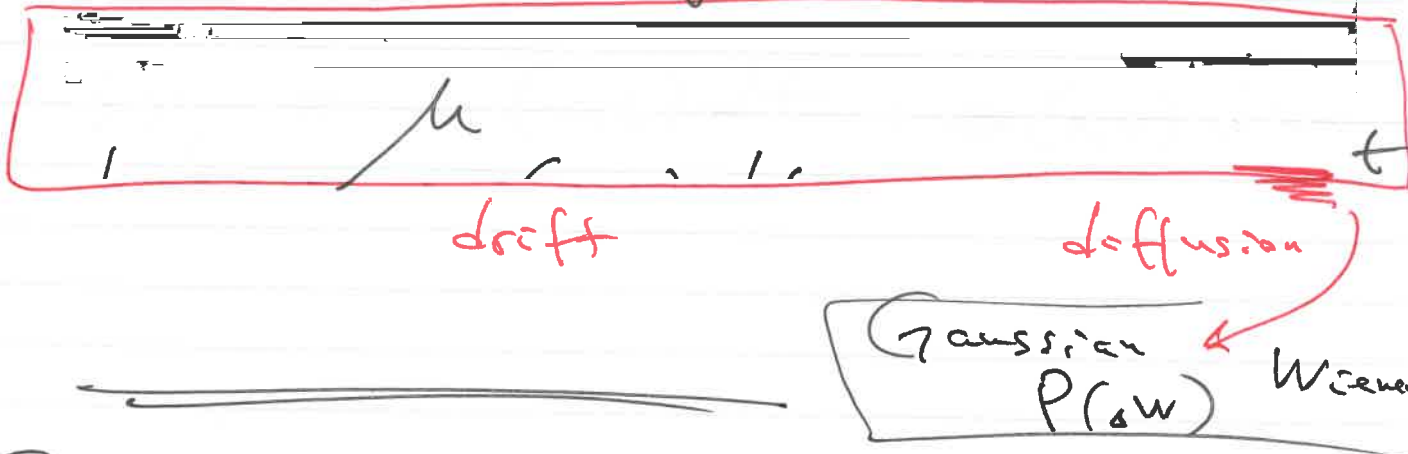
More generally:

SDE $\frac{dx}{dt} = F(x) + \sigma(x) \xi(t)$

drift term diffusion term
 or noise
 Wiener process

$$\sigma = \frac{1}{2} \epsilon^2$$

Mathematical format of SDE



Example of SDE:

Geometric Brownian Motion

Multiplicative

Wiener

SDE:
$$dS_t = (\underbrace{\mu \cdot S_t}_{\text{constant}}) dt + (\underbrace{\sigma \cdot S_t}_{\text{constant}}) dW_t$$

$$\frac{dS}{S} = \mu dt + \sigma dW$$

looks like

$d(\ln S)$

looks like simple Brownian motion...

But we discover that a lot is hidden...

Itoh Lemma

if we have a stochastic process $X(t)$, with SDE

$$dX_t = \mu dt + \sigma dW_t$$

and there is a function $f(x)$, then what is its SDE?

$$df = f(x+dx) - f(x)$$

Chain rule

~~$f(x) = f(x) + \frac{\partial f}{\partial x} dx + \frac{1}{2} \frac{\partial^2 f}{\partial x^2} dx^2 + \dots$~~

We only want terms linear in (dt) , not higher-order.

none there

$$\approx \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} (\mu dt + \sigma dW)$$

$$+ \frac{1}{2} \frac{\partial^2 f}{\partial x^2} (\mu^2 dt^2 + 2\mu\sigma dt dW + \sigma^2 dW^2)$$

small

$$\approx \frac{\partial f}{\partial t} dt + \frac{\partial f}{\partial x} (\mu dt + \sigma dW)$$

assume fast steps

$$+ \frac{1}{2} \frac{\partial^2 f}{\partial x^2} \sigma^2 dW^2 \dots \langle dW^2 \rangle = dt$$

So we have:

$$df = \left(\frac{\partial f}{\partial t} + \mu \frac{\partial f}{\partial x} + \frac{1}{2} \sigma^2 \frac{\partial^2 f}{\partial x^2} \right) dt + \sigma \frac{\partial f}{\partial x} dW$$

drift term

diffusion term

Ito's Lemma!

Now: GBM

$$dS = \mu S dt + \sigma S dW$$

and $f(S) = \ln(S)$

$$d[\ln(S)] = \frac{\partial f}{\partial S} dS + \frac{1}{2} \frac{\partial^2 f}{\partial S^2} dS^2$$

$$= \frac{dS}{S} - \frac{1}{2S^2} dS^2$$

$$= \frac{dS}{S} - \frac{1}{2S^2} \left(\cancel{\mu^2 S^2 dt^2} + 2\mu\sigma S^2 dt dW + \sigma^2 S^2 dW^2 \right) dt$$

$$d[\ln(S)] = \left(\mu - \frac{1}{2}\sigma^2 \right) dt + \sigma dW$$

gives $S = S_0 e^{(\mu - \frac{\sigma^2}{2})t + \sigma W}$

Stochasticity (σ)

Look here!

Can reduce, or even revert exponential growth $e^{\mu t}$...

Still Stochastic

Lecture 5

We just did "Itôh Lemma"
and looked at
"GBM" $ds = \mu s dt + \sigma s dW$

Entry level of financial application:

"Black-Scholes equation"

→ Nobel Prize 1997 (also to Merton)

Analysis of dynamics and
prediction of option prices
in a volatile market.

How to decide on a "portfolio"

to buy: exchange risk for cash

Crisis 1987

→ Traders colluded to
punish the early
adopters of B-S.

Crisis 2008

→ Too much trust
into B-S analysis,
incorred use of it

"Stock" $S(t)$: value of shares

$$dS = \mu S dt + \sigma S dW$$

"Option" is a contract when
on (seller) agree to sell

some stock $S(t)$ at a

future time t , at a

current price (s)

buyer have to a a

fee for this: $V(s)$.

Obvious $V(s, t)$ and $V(t=0) = 0$

⊙ How to estimate best $V(s)$

"Port (co)" of this transaction
is what buyer has:

cash \curvearrowright

$$\Pi = -V(s) + \alpha S$$

(paid) \searrow \nearrow (cash is some stock)

is called "hedging"

In continuous trading, we have small
increments

$$\Delta \Pi = -\Delta V(s) + \alpha \Delta S$$

Itoh Lemma Says:

$$dV(s) = \left(\frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial s} ds + \frac{1}{2} \frac{\partial^2 V}{\partial s^2} ds^2 \right)$$

$$dV = \left(\frac{\partial V}{\partial t} + \mu s \frac{\partial V}{\partial s} + \frac{1}{2} \sigma^2 s^2 \frac{\partial^2 V}{\partial s^2} \right) dt$$

$$+ \sigma s \frac{\partial V}{\partial s} dW$$

Now put this back into dTT:



$$+ \left(\alpha \sigma s - \sigma s \frac{\partial V}{\partial s} \right) dW$$

fluctuating part

We can choose the factor α such that the bracket = 0!

$$\alpha = \frac{\partial V}{\partial s}$$

① Then no volatility left in dTT

Now we wish to build the equation for $V(s)$, using some model Π .

Determine the l.h.s. $d\pi$:

we need to make a decision on what we want to achieve:

$$d\pi = r \cdot \pi dt$$

we "deal in" the rate of growth.

What is the lowest risk-free rate of growth?

l.h.s.

r.h.s.

$$r(\alpha S - V) dt = \left(-\frac{\partial V}{\partial t} - \mu S \frac{\partial V}{\partial S} - \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} + \alpha \mu S \right) dt$$

($\alpha = \frac{\partial V}{\partial S}$)

Finally we have: with initial $V(t=0) = 0$

$$\frac{\partial V(S,t)}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} = V - S \frac{\partial V}{\partial S}$$

is is B-S equation for $V(S,t)$. To solve it we need to know μ and σ , but note that μ has disappeared ...

1) Consider the simplest: $r=0$

$$\frac{\partial V}{\partial t} + \frac{\sigma^2}{2} S^2 \frac{\partial^2 V}{\partial S^2} = 0$$

has known solutions

① we are certain we know σ ?
All of the modern science is about more accuracy

② Some standard maths of B.S.E.

A Substitution: S - stock now

define $x = \ln(S/E)$ E - stock at the end $(t=0)$
 $(t=T)$

$$or \quad 0 = r - \sigma^2 x$$

e^x

(C) Then call

$$u(x,t) = Z(x,\tau) \cdot e^{\beta x + \gamma \tau}$$

then

enter new parameters

~~$$\frac{\partial u}{\partial t} - \frac{\sigma^2}{2} \frac{\partial^2 u}{\partial x^2} + A(\beta, \gamma) \cdot \frac{\partial u}{\partial x} + B(\beta, \gamma) \cdot u = 0$$~~

(β, γ)

choose β, γ
such that

$$+ B(\beta, \gamma) \cdot u = 0$$

$$A = 0, B = 0$$

$$\beta = r/\sigma^2 - 1/2$$

$$\gamma = r/2 + \sigma^2/8 + r^2/2\sigma^2$$

then just
simple diffusion eq.

$$\frac{\partial u}{\partial \tau} = \frac{\sigma^2}{2} \frac{\partial^2 u}{\partial x^2}$$

$$u(x,\tau) = \int \frac{1}{\sqrt{2\pi\sigma^2\tau}} e^{-\frac{(x-w)^2}{2\sigma^2\tau}} u(w,0) dw$$

when $x(\tau=0) = w$

then roll back substitutions:

first $Z(x,\tau)$ from $u(x,\tau)$,

then $V(S,t)$

The Heston Model – The Physics of Stochastic Volatility Models

Date **Friday, 9 February**
Time **11:00 a.m. - 12:00 p.m.**
Room **Bragg Building, Small Lecture Theater**

Open to all Cambridge students

Join us for an exclusive lecture by Optiver on financial modeling. Dive into the complexities of the Heston model, a cornerstone in stochastic volatility modeling, and discover how it revolutionizes our understanding of financial markets.

Key agenda points

- Comprehensive overview of the Heston model's dynamic properties
- In-depth analysis of the affine structure inherent to the model
- Partial Differential Equations (PDEs) and Ordinary Differential equations (ODEs) of the model
- Practical application: Characteristic function in option pricing

About the lecturer



Fabio Maggioni is an **Optiver quantitative researcher** working on the development and improvement of new pricing models and techniques. The focus of his research is around the impact of rate and volatility term structure and dividend uncertainty on the early exercise of American options. He joined Optiver after earning a Master's Degree in Mathematical Engineering at Polytechnic University of Milan.

Heston model

The physics of stochastic volatility models



Heston model

The physics of stochastic volatility models

Beyond Black-Scholes assumptions

Definition

Dynamics

Partial Differential Equation

Characteristic function





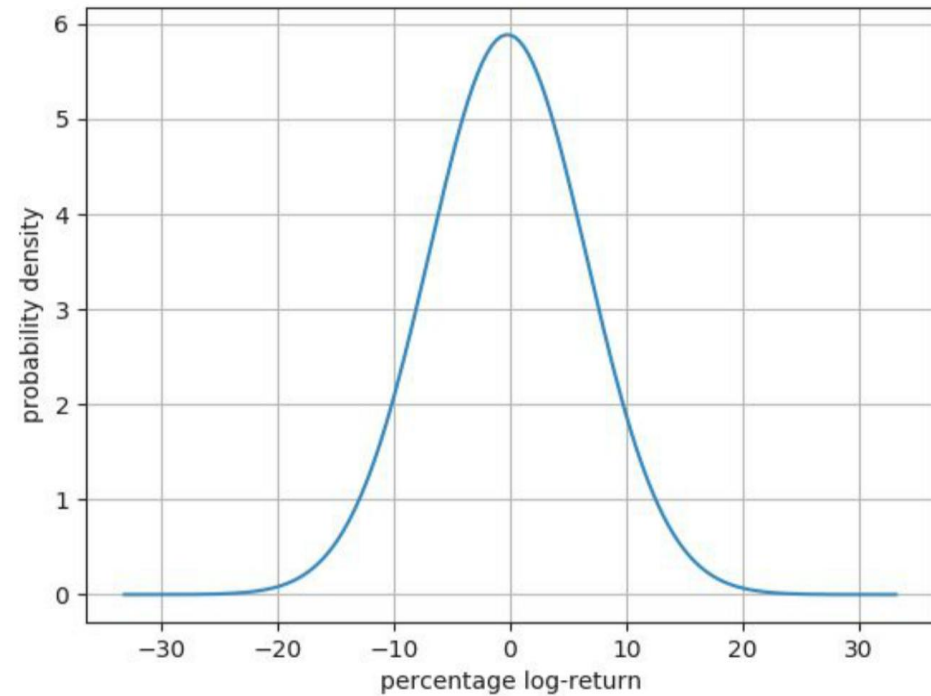
Beyond Black-Scholes

Pros	Cons	Market
<p>Closed form solution for option prices</p> <p>Mathematical tractability</p> <p>Great for communication</p>	<p>Uncorrelated log-returns</p> <p>Gaussian log-returns</p>	<p>Persistence of variability (high vol and low vol periods)</p> <p>Spot-vol correlation</p> <p>Fat tailed log-return (kurtosis and skew)</p>

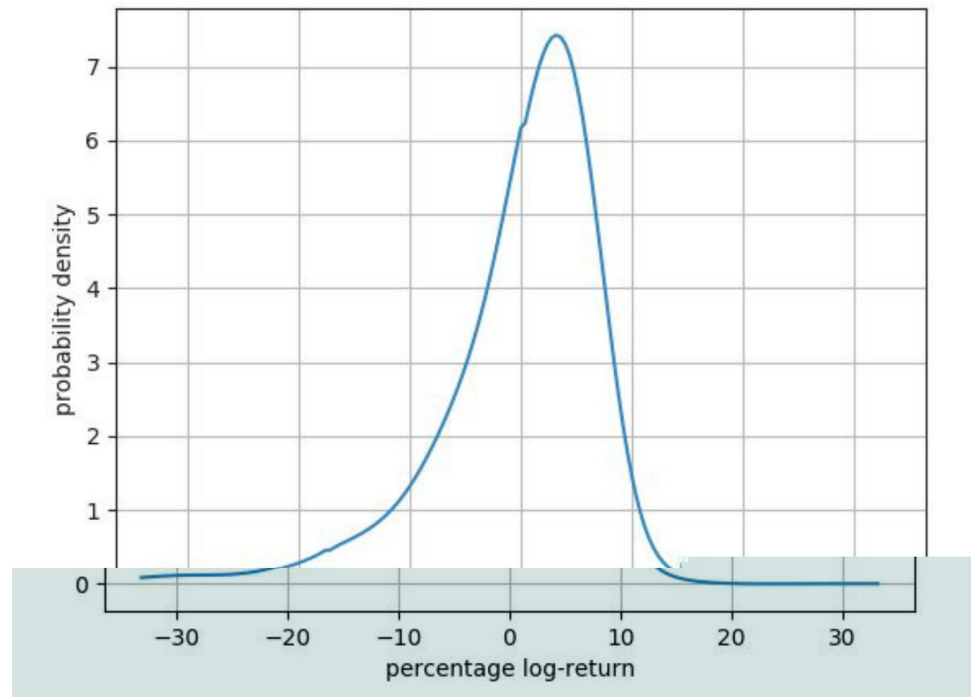


Log-return distribution

Black-Scholes



Financial markets



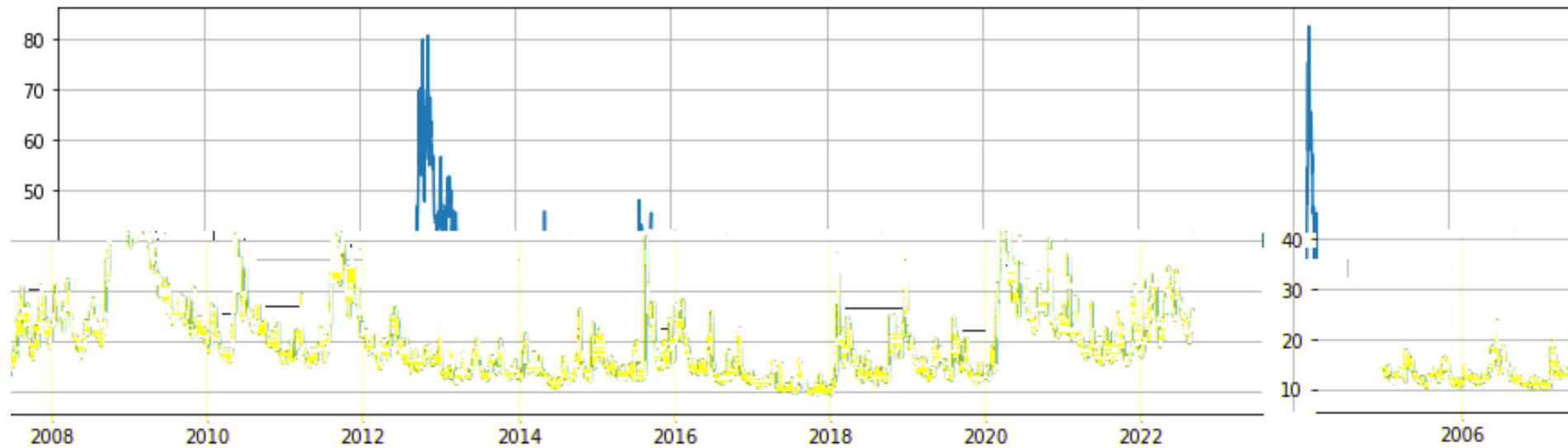


More complex models

$$dS_t = rS_t dt + \sigma_t S_t dW_t$$

Deterministic time dependent volatility does not improve over normality of log returns

Looking at Volatility Index we can guess that volatility is a good place to start: stochastic volatility models!





Stochastic volatility models

Setting:

$$\begin{aligned}dS_t &= rS_t dt + \sigma_t S_t dW_t^1 \\d\sigma_t &= a(t, \sigma_t)dt + b(t, \sigma_t) dW_t^2\end{aligned}$$

With dW^1 and dW^2 being possibly correlated (ρ) random increments and a b

According to the structure of functions a and b we can produce all sort of dynamics for the vol.

Which one is appropriate?



Heston

$$\left| \begin{aligned} dS_t &= rS_t dt + S_t\sqrt{v_t} dW_t^1 \\ dv_t &= \kappa(\bar{v} - v_t) dt + \gamma\sqrt{v_t} dW_t^2 \\ S_{t_0} &= S_0 \\ v_{t_0} &= v_0 \\ E[dW_t^1 dW_t^2] &= \rho dt \end{aligned} \right.$$

κ = speed of mean reversion in years

\bar{v} = long term variance

v_0 = short term variance

γ = vol of vol

ρ = spot – variance correlation



Heston

$$\begin{cases} dS_t = rS_t dt + S_t\sqrt{v_t} dW_t^1 \\ dv_t = \kappa(\bar{v} - v_t) dt + \gamma\sqrt{v_t} dW_t^2 \end{cases}$$

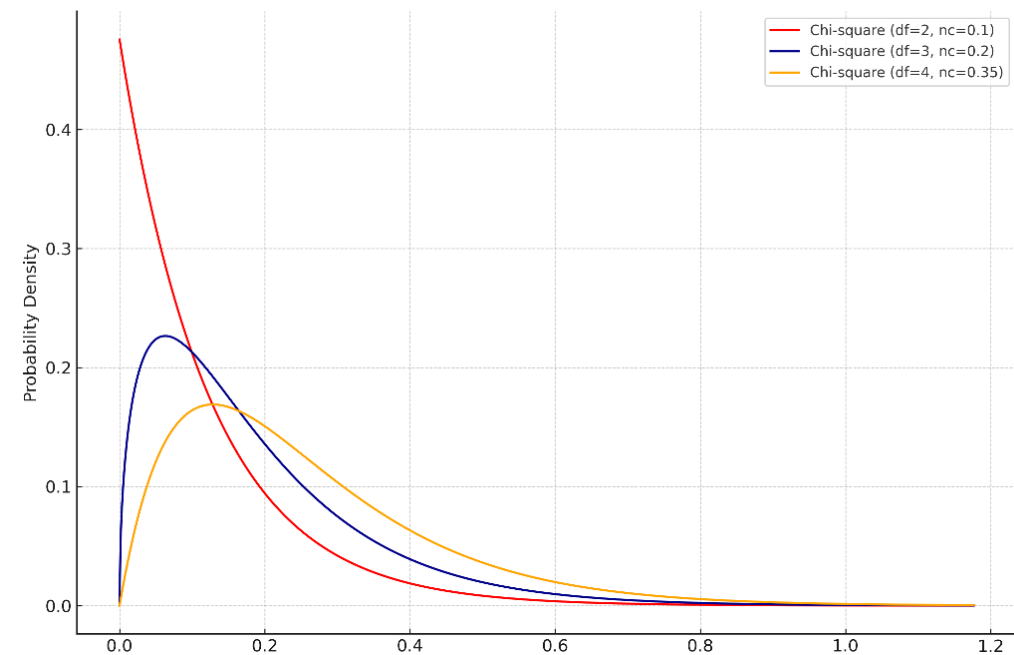
Instantaneous variance v_t is mean reverting

Instantaneous volatility $\sqrt{v_t}$ has 2 sources of randomness:

Spot level via correlation ρ

Exogenous variance process guided by vol of vol γ

Variance is distributed as a scaled Non central Chi square





Dynamics at the limit

Let's look at some key quantities of the Heston model for an expiry time T .

$$E[v_T|v_0] = v_0 e^{-\kappa T} + \bar{v}(1 - e^{-\kappa T})$$

$$Var[v_T|v_0] = v_0 \frac{\gamma^2}{\kappa} (e^{-\kappa T} - e^{-2\kappa T}) + \frac{\bar{v}\gamma^2}{2\kappa} (1 - e^{-\kappa T})^2$$

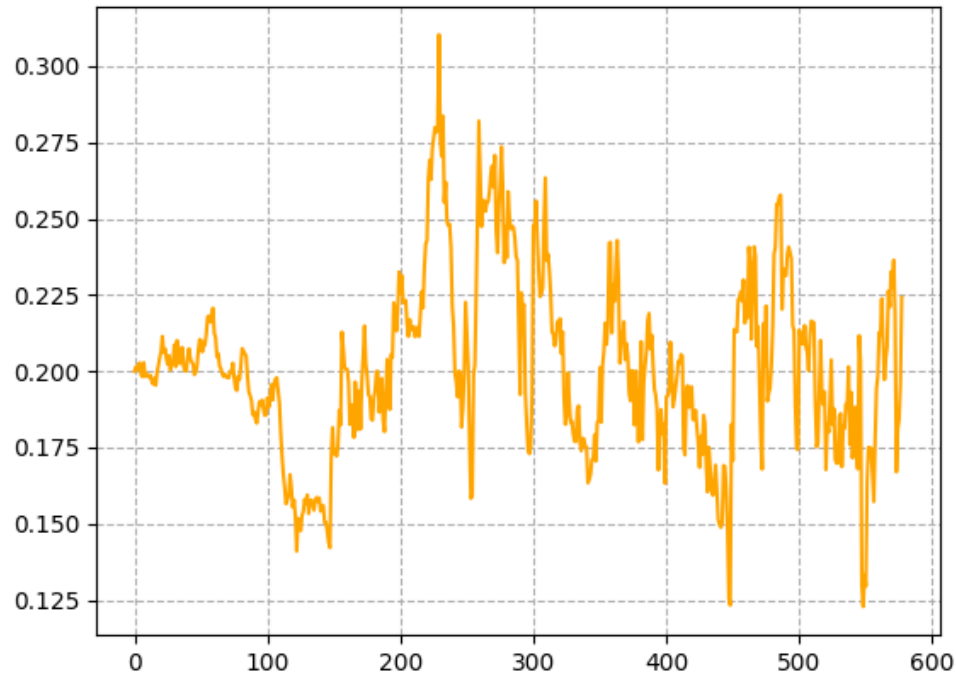
For $\kappa \rightarrow \infty$, $E[v_t|v_0] \rightarrow \bar{v}$, $Var[v_t|v_0] \rightarrow 0$, Heston \rightarrow Black&Scholes with $\sigma^2 = \bar{v}$

For $\gamma \rightarrow 0$, $E[v_t|v_0] = v_0 e^{-\kappa t} + \bar{v}(1 - e^{-\kappa t})$, $Var[v_t|v_0] \rightarrow 0$, Heston \rightarrow Black&Scholes with deterministic term structure

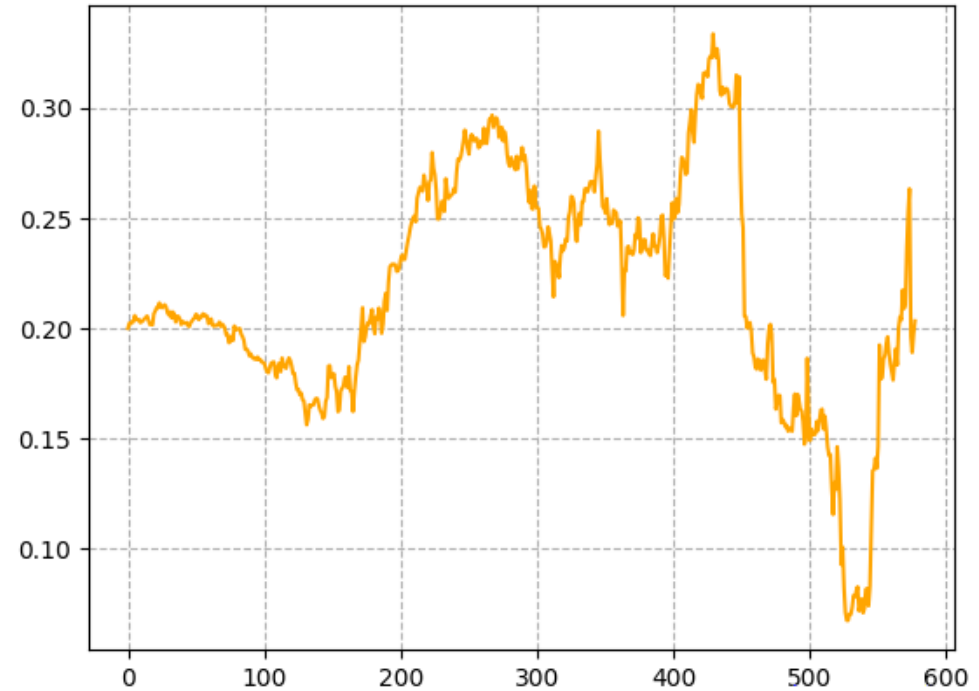


Variance dynamics

Variance process



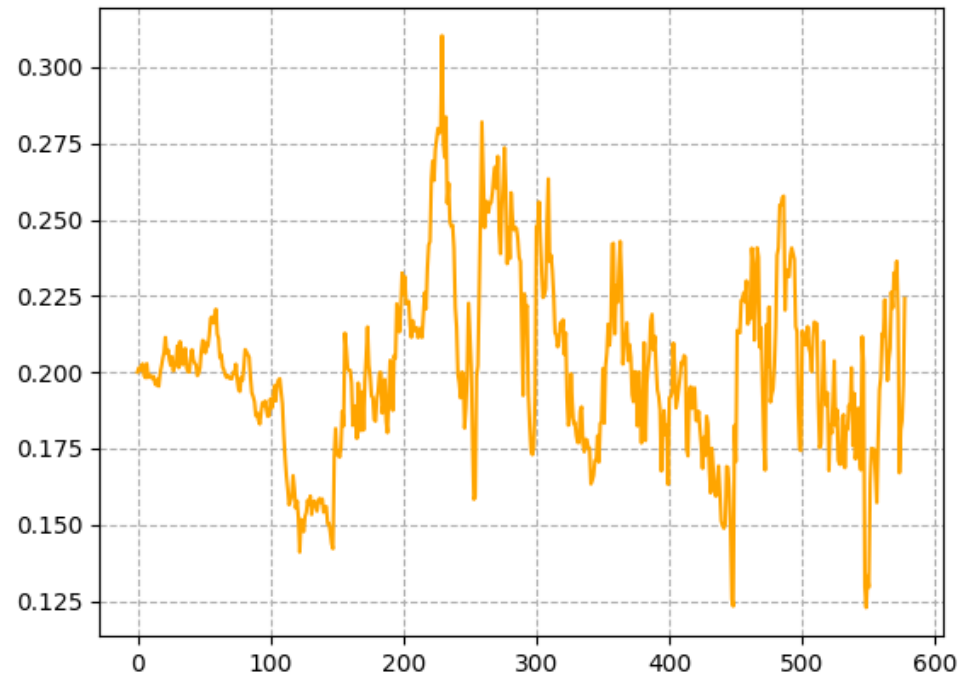
Variance process





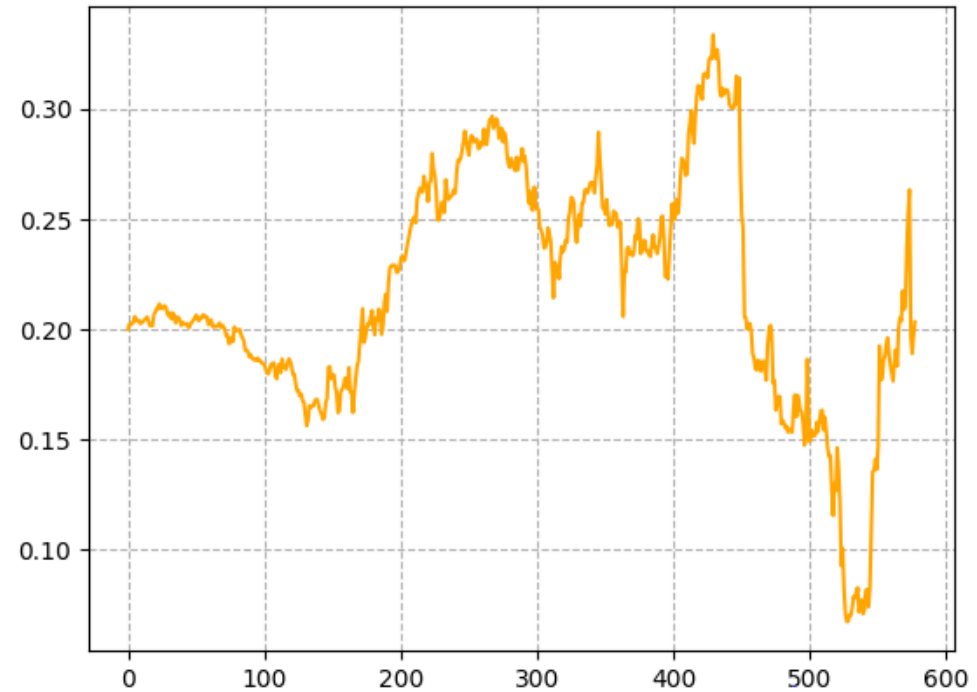
Variance dynamics

Variance process



High mean reversion

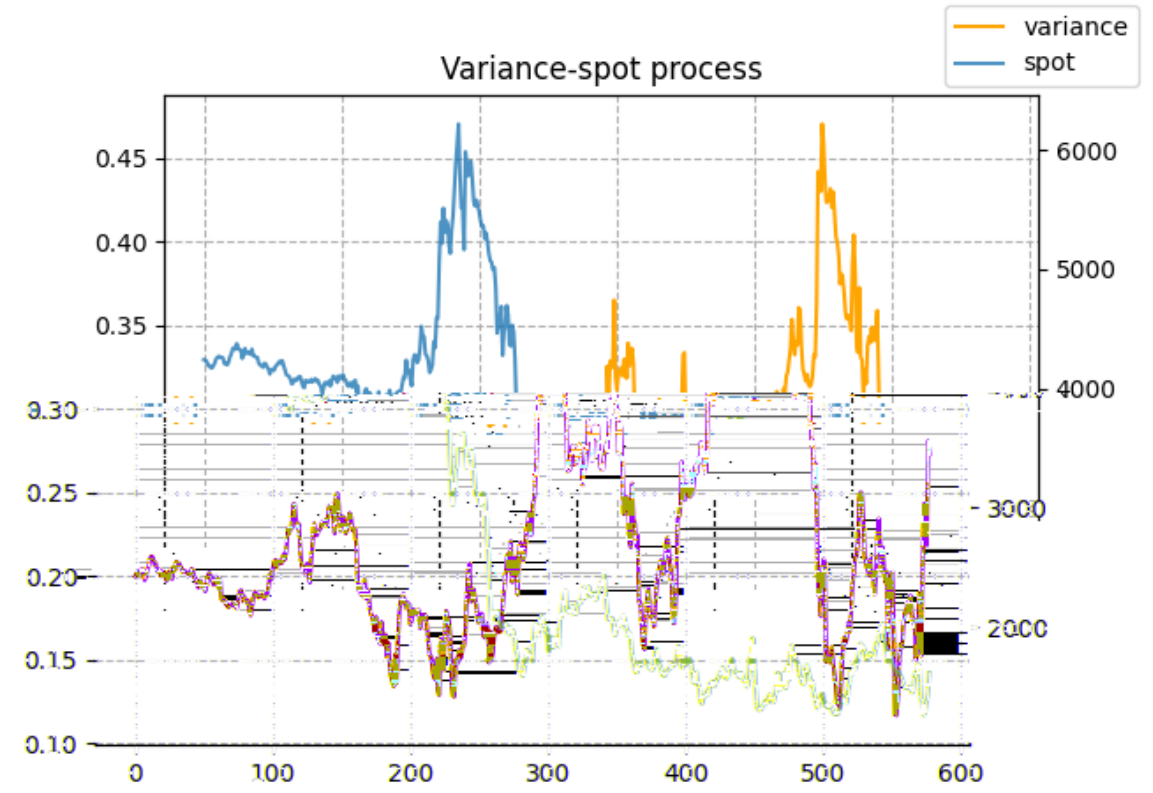
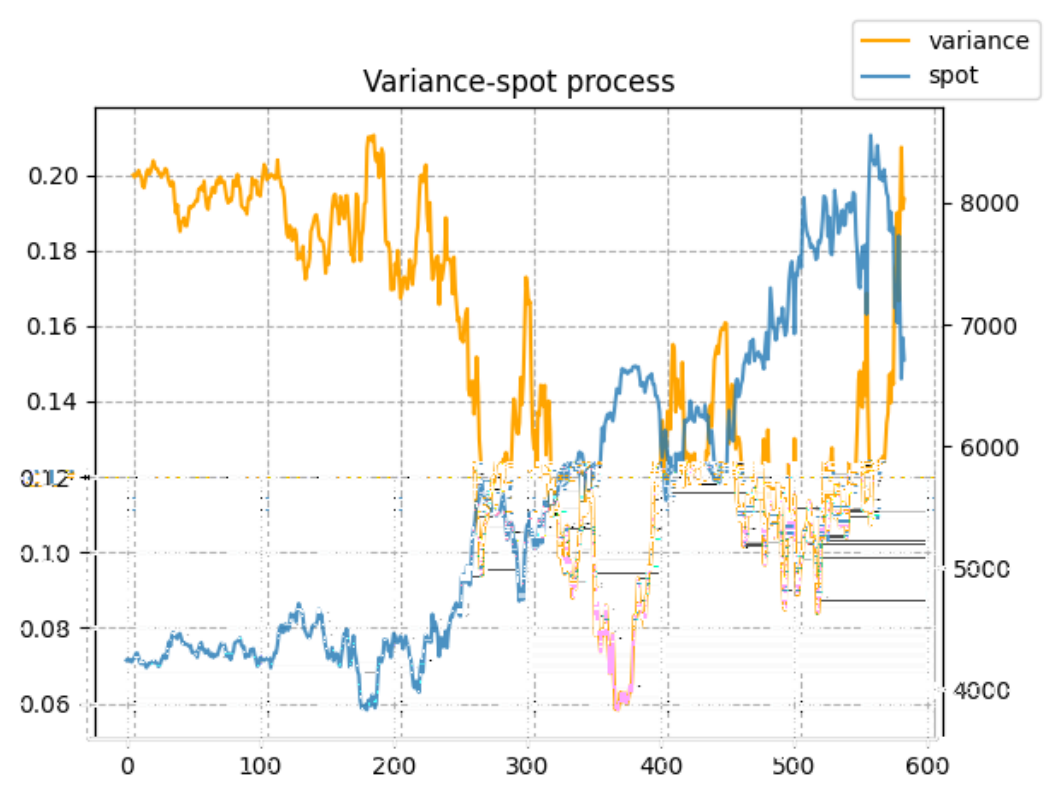
Variance process



Low mean reversion

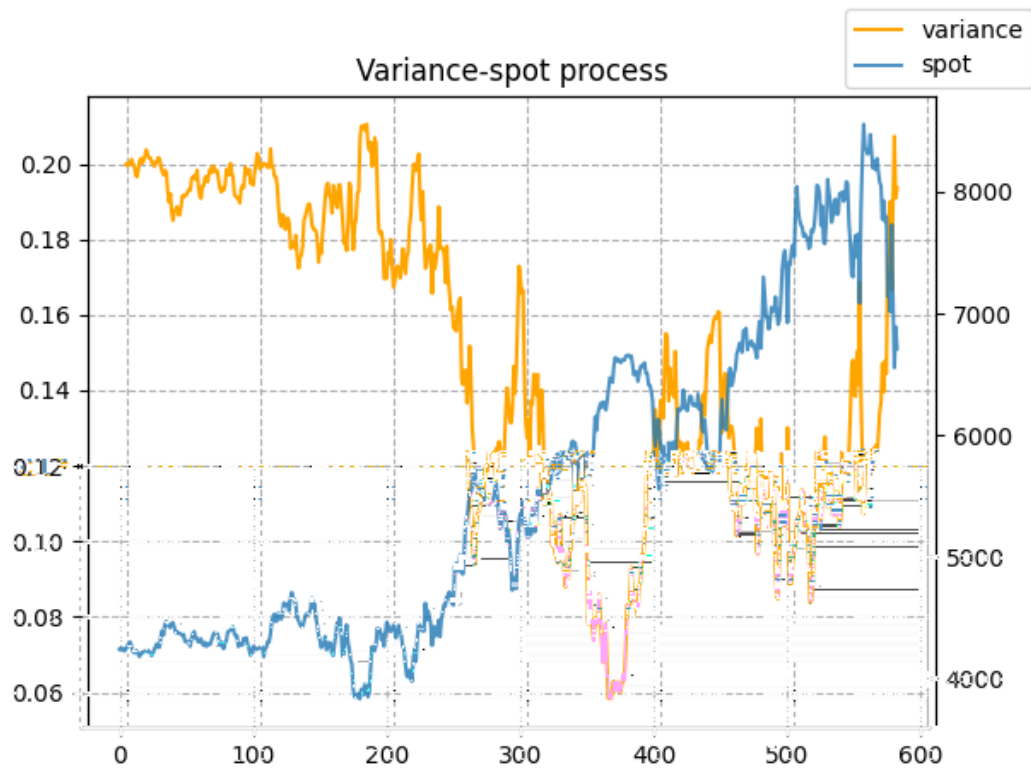


The Joint dynamics

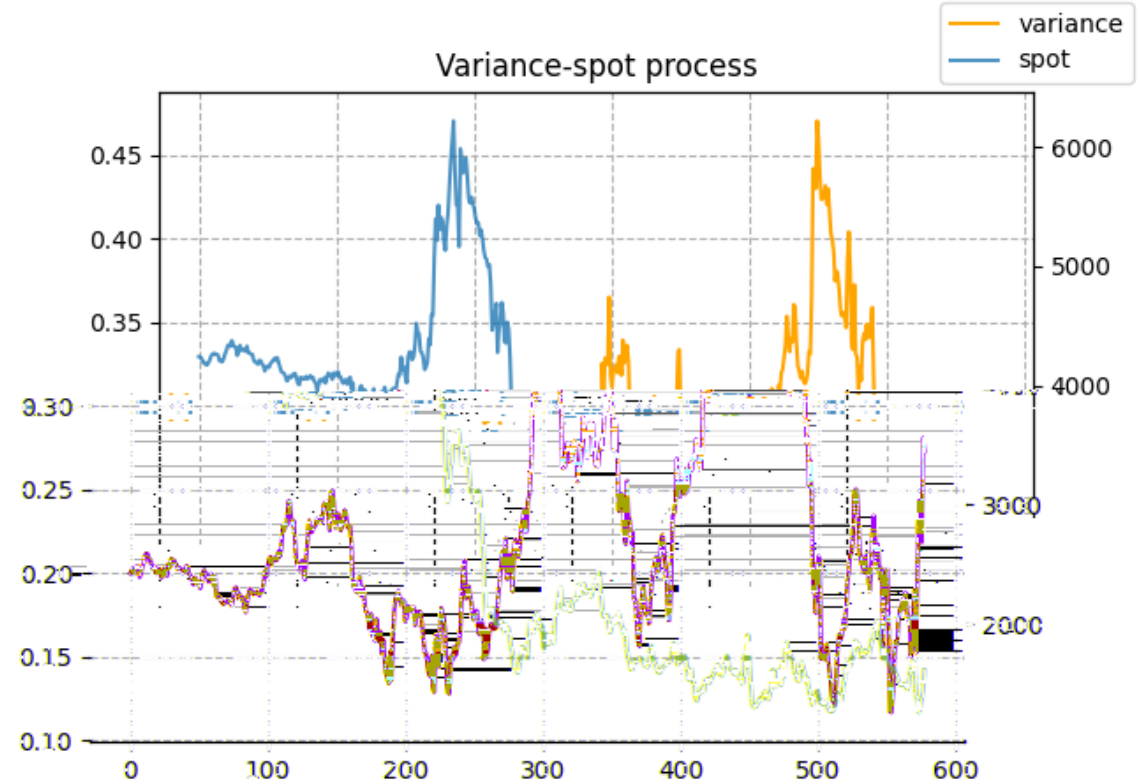




The Joint dynamics



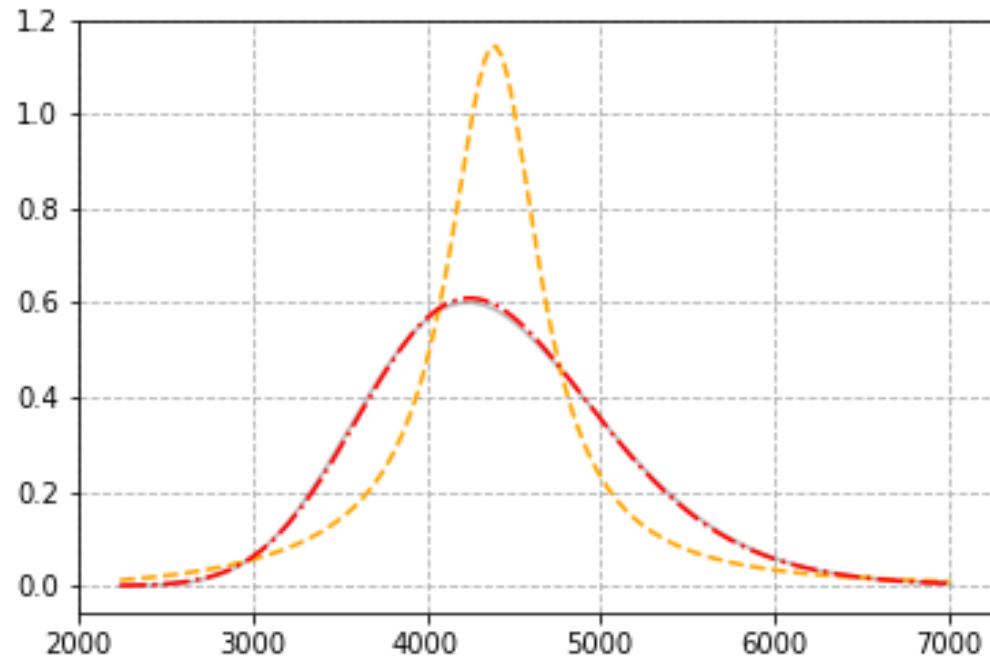
Variance-spot correlation



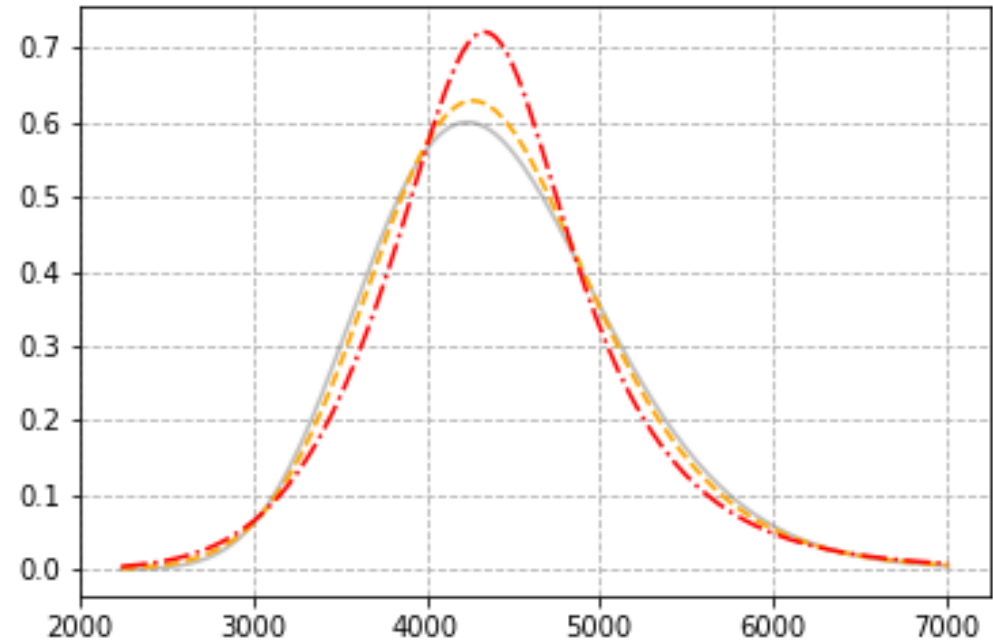
No variance-spot correlation



Heston stock distribution



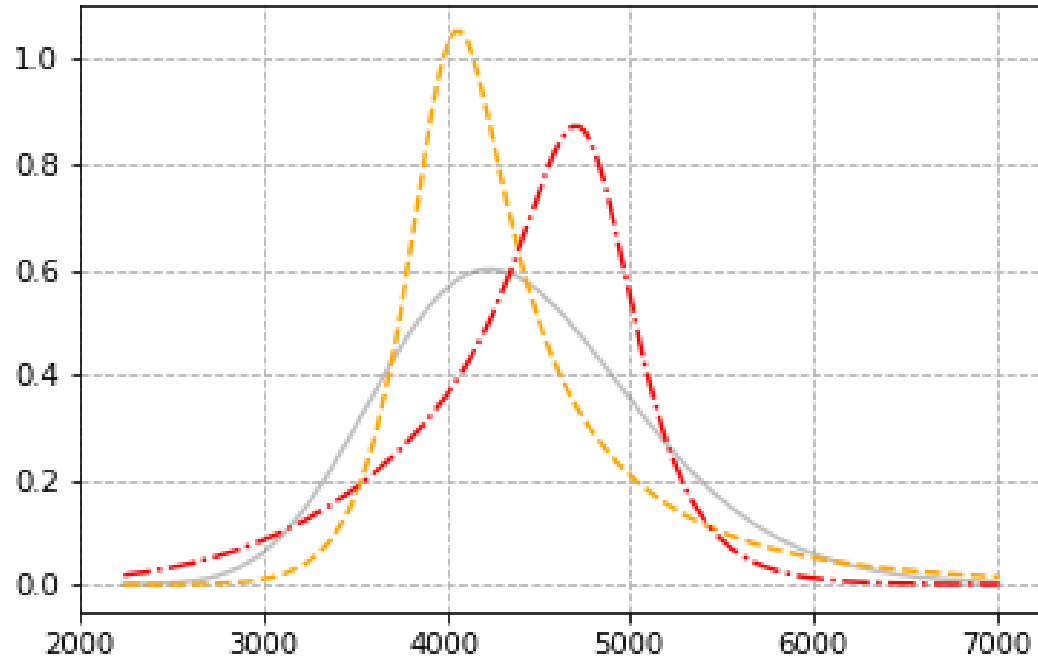
Vol of vol = 0.1
Vol of vol = 0.7



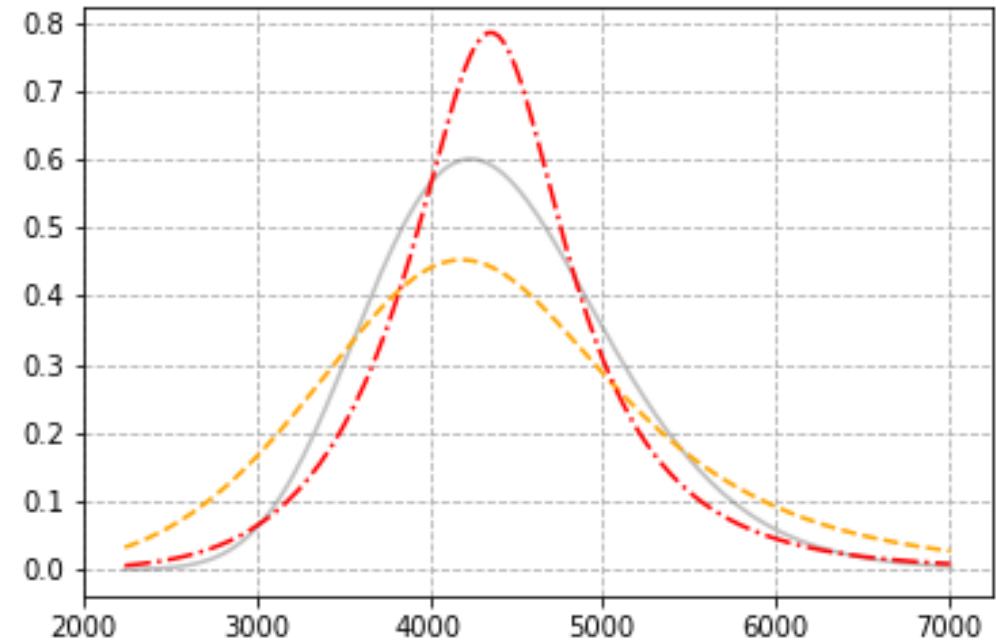
Mean reversion = 0.1
Mean reversion = 0.3



Heston stock distribution



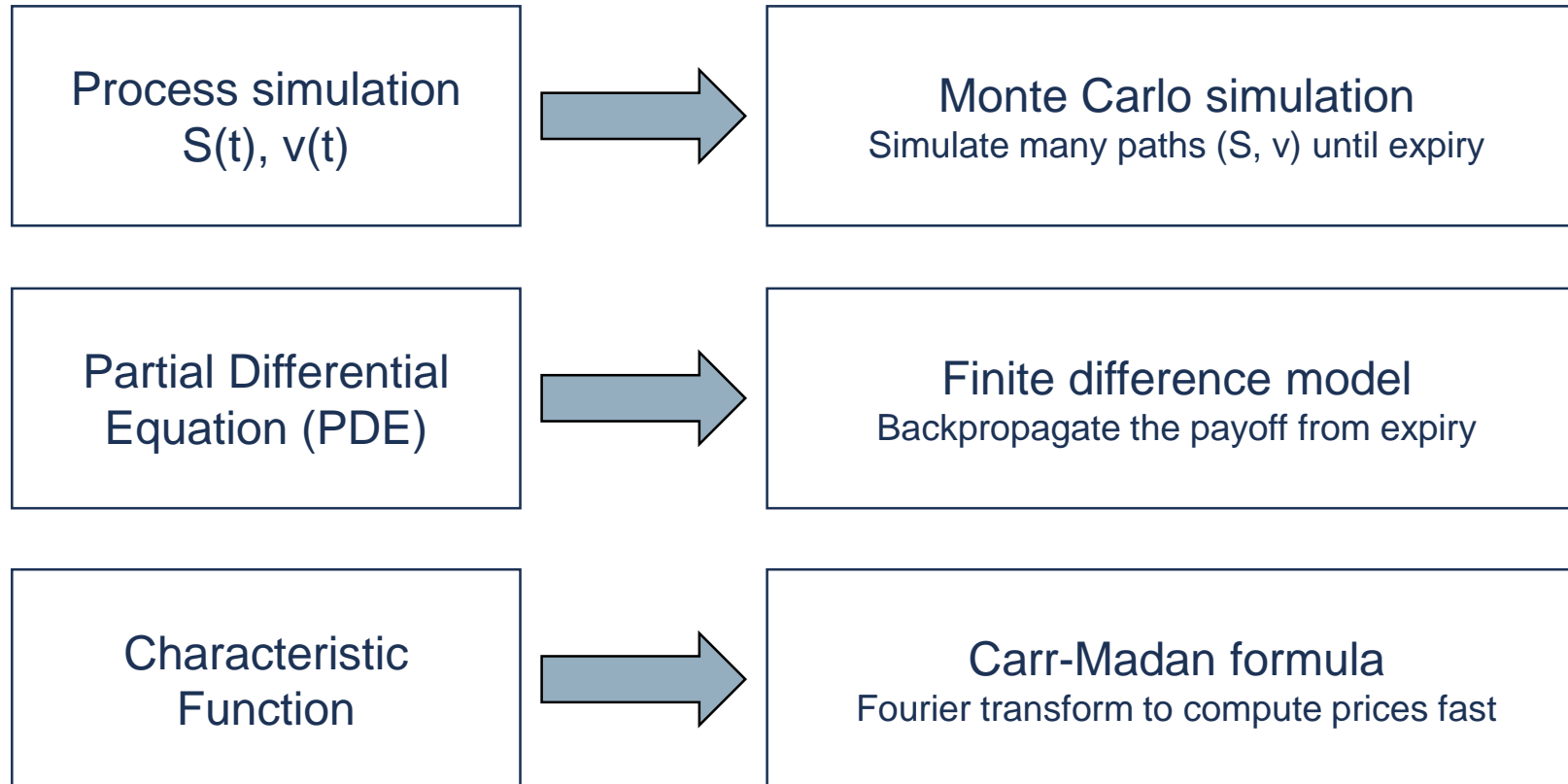
$\rho = -0.7$ Left skew
 $\rho = 0.7$ Right skew



$v_0 = 0.04$
 $v_0 = 0.1$



Heston model – How to deal with it?





Heston model

Black-Scholes model 2 parameters, 1d process:

$$dS = rS dt + \sigma S dW$$
$$S(t = 0) = S_0$$

Heston model dynamics 6 parameters, 2d process:

$$dS = rS dt + \sqrt{v}S dW_S$$
$$dv = \kappa(\bar{v} - v) dt + \gamma\sqrt{v} dW_v$$
$$E[dW_S dW_v] = \rho dt$$
$$S(t = 0) = S_0$$
$$v(t = 0) = v_0$$



Decorrelating correlated Brownian motions

$$dW_S = dW_1$$

Expectation and variance matches, so far so good

$$dW_v = a dW_1 + b dW_2$$

Expectation:

$$E[dW_v] = E[a dW_1 + b dW_2] = aE[dW_1] + bE[dW_2] = 0 + 0 = 0$$

Variance:

$$\text{Var}(dW_v) = \text{Var}(a dW_1 + b dW_2) = E[a^2 dW_1^2 + 2ab dW_1 dW_2 + b^2 dW_2^2] = a^2 dt + b^2 dt \Rightarrow a^2 + b^2 = 1$$

Covariance:

$$\text{Cov}(dW_S, dW_v) = \text{Cov}(dW_1, a dW_1 + b dW_2) = E[a dW_1^2 + b dW_1 dW_2] = a dt \Rightarrow a = \rho \Rightarrow b = \sqrt{1 - \rho^2}$$



Decorrelating correlated Brownian motions

Matrix notation:

$$\begin{pmatrix} 1 & 0 \\ \rho & \sqrt{1-\rho^2} \end{pmatrix} \begin{pmatrix} dW_1 \\ dW_2 \end{pmatrix} = \begin{pmatrix} dW_S \\ dW_v \end{pmatrix}$$

Monte Carlo simulation discretizing:

$$\begin{cases} dS = rS dt + \sqrt{v}S dW_1 \\ dv = \kappa(\bar{v} - v)dt + \gamma\sqrt{v}(\rho dW_1 + \sqrt{1-\rho^2} dW_2) \end{cases}$$



Heston PDE derivation

Heston model SDE:

$$\begin{cases} dS = rS dt + \sqrt{v}S dW_1 \\ dv = \kappa(\bar{v} - v)dt + \gamma\sqrt{v}(\rho dW_1 + \sqrt{1 - \rho^2} dW_2) \end{cases}$$

Option price should change over time (on expectation) same as value of money martingale (no-arbitrage):

$$e^{-rt}V(t, S(t), v(t)) = e^{-rT}E[V(T, S(T), v(T))]$$

$$\begin{aligned} d(e^{-rt}V) &= e^{-rt}dV - re^{-rt}Vdt \\ &= e^{-rt} \left(\frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial S} dS + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} dS^2 + \frac{\partial V}{\partial v} dv + \frac{1}{2} \frac{\partial^2 V}{\partial v^2} dv^2 + \frac{\partial^2 V}{\partial S \partial v} dSdv \right) - re^{-rt}Vdt \end{aligned}$$



Heston PDE derivation

$$\left| \begin{aligned} dS &= rS dt + \sqrt{v}S dW_1 \\ dv &= \kappa(\bar{v} - v) dt + \gamma\sqrt{v}(\rho dW_1 + \sqrt{1 - \rho^2} dW_2) \end{aligned} \right.$$

$$\begin{aligned} d(e^{-rt}V) &= e^{-rt} \left(\frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial S} dS + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} dS^2 + \frac{\partial V}{\partial v} dv + \frac{1}{2} \frac{\partial^2 V}{\partial v^2} dv^2 + \frac{\partial^2 V}{\partial S \partial v} dS dv \right) - re^{-rt}V dt = \\ &= e^{-rt} \left(\frac{\partial V}{\partial t} dt + \frac{\partial V}{\partial S} (rS dt + \sqrt{v}S dW_1) + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} vS^2 dt + \frac{\partial V}{\partial v} (\kappa(\bar{v} - v) dt + \gamma\sqrt{v}(\rho dW_1 + \sqrt{1 - \rho^2} dW_2)) \right. \\ &\quad \left. + \frac{1}{2} \frac{\partial^2 V}{\partial v^2} \gamma^2 v dt + \frac{\partial^2 V}{\partial S \partial v} \gamma v S \rho dt \right) - re^{-rt}V dt \end{aligned}$$

On expectation this change should equal zero. $E[dW] = 0$, so we only need to take care of dt terms:

$$\frac{\partial V}{\partial t} + \frac{\partial V}{\partial S} rS + \frac{1}{2} \frac{\partial^2 V}{\partial S^2} vS^2 + \frac{\partial V}{\partial v} \kappa(\bar{v} - v) + \frac{1}{2} \frac{\partial^2 V}{\partial v^2} \gamma^2 v + \frac{\partial^2 V}{\partial S \partial v} \gamma v S \rho - rV = 0$$



Affine processes

Given a d dimensional process X

$$dX = \mu(t, X)dt + \sigma(t, X)dW$$

Characteristic function exponentially affine:

$$\phi(v, t, T) = E[e^{-\int_t^T r(s)ds + iu^T X(T)}] = e^{A(u, T-t) + B^T(u, T-t)X(T)}$$

Necessary condition:

$$\mu(t, X) = a^0 + a^1 X$$

$$[\sigma(t, X)\sigma^T(t, X)]_{ij} = c_{ij}^0 + \sum_k c_{ij_k}^1 X_k$$

Drift and covariance matrix at most linear in all coefficients



Heston – affine process in $\log(S)$

$$X = \log(S)$$

$$d \begin{pmatrix} X \\ v \end{pmatrix} = \begin{pmatrix} r - \frac{1}{2}v \\ \kappa\bar{v} - \kappa v \end{pmatrix} dt + \begin{pmatrix} \sqrt{v} & 0 \\ \rho\gamma\sqrt{v} & \gamma\sqrt{1-\rho^2}\sqrt{v} \end{pmatrix} d \begin{pmatrix} W_1 \\ W_2 \end{pmatrix}$$
$$\sigma\sigma^T = \begin{pmatrix} v & \rho\gamma v \\ \rho\gamma v & \gamma^2 v \end{pmatrix}$$

PDE in terms of X and $\tau = T - t$:

$$-\frac{\partial V}{\partial \tau} + \left(r - \frac{1}{2}v\right) \frac{\partial V}{\partial X} + \frac{1}{2}v \frac{\partial^2 V}{\partial X^2} + \kappa(\bar{v} - v) \frac{\partial V}{\partial v} + \frac{1}{2}\gamma^2 v \frac{\partial^2 V}{\partial v^2} + \gamma v \rho \frac{\partial^2 V}{\partial X \partial v} - rV = 0$$



Heston model characteristic function

Chf:

$$e^{-rt} \phi(u, t, T) = e^{-rT} E[e^{iuX(T)}]$$

Solution ansatz:

$$\phi(u, t, T) = e^{A(u, \tau) + B(u, \tau)X + C(u, \tau)v}$$

Initial (final) conditions:

$$\phi(u, T, T) = e^{iuX(T)} \Rightarrow A(u, 0) = C(u, 0) = 0, B(u, 0) = iu$$

$$\frac{dB}{d\tau} = 0$$

$$\frac{dC}{d\tau} = \frac{1}{2}B(B-1) - (\kappa - \gamma\rho B)C + \frac{1}{2}\gamma^2 C^2$$

$$\frac{dA}{d\tau} = \kappa\bar{v}C + r(B-1)$$



Call option price and characteristic function

Call price:

$$C(K) = E[\max(S_T - K, 0)] = \int_0^{+\infty} \max(s - K) f(s) ds$$

We know the characteristic function in close form, but not the density. Using the Fourier Transform:

$$C(K) = F_\alpha^{-1}[F_\alpha[C]](k) = \frac{e^{-\alpha k}}{2\pi} \int_{-\infty}^{+\infty} e^{-ivk} \frac{\phi(v - i(\alpha + 1))}{(\alpha + iv)(\alpha + iv + 1)} dv$$

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Thank you!

Do you have any questions?



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Lecture 7 "back to physics" ...

Ornstein - Uhlenbeck process

General SDE: $dx_t = \mu(x,t) dt + \sigma(x,t) dW$

O-U process is when

Normalised
Wiener process

$$dx_t = -\theta(x-x_0) dt + \sigma dW$$

we are familiar with

constants

$$m\dot{v} = -\gamma v + \sqrt{2kT\gamma} \xi(t)$$

Also overdamped:

$$\gamma \dot{x} = -k(x-x_0) + \sqrt{2kT\gamma} \xi(t)$$

spring force

All physical systems near equilibrium ...

So standard form

$$dx_t = -\frac{k}{\gamma}(x-x_0) dt + \sqrt{\frac{2kT}{\gamma}} dW$$

Note: $x(t) = \int_0^t v(s) ds$

$$\langle x^2(t) \rangle = \int_0^t ds_1 \int_0^t ds_2 \langle v(s_1) v(s_2) \rangle$$

$$\frac{d}{dt} \langle x^2(t) \rangle = 2 \int_0^t ds \langle v(t) v(s) \rangle$$

ensemble averaging at fixed t .

for free diffusion
 $\langle x^2 \rangle = 2Dt$

depends on $t-s = \tau$

$$D = \int_0^t \langle v(t) v(s) \rangle ds = \int_0^t \langle v(s) v(0) \rangle ds$$

Also: go back to free-diffusion SDE
 multiply it by $v_0 = \text{const}$, $\langle \dots \rangle$

$$m \frac{d}{dt} \langle v(t) \cdot v_0 \rangle = -\gamma \langle v(t) v_0 \rangle, \text{ hence } \langle v_0^2 \rangle = 0$$

$$\langle v(t) v(0) \rangle = v_0^2 \cdot e^{-\gamma/m t}$$

$\langle v_0^2 \rangle$: ensemble average with $p(v)$

"Memory" of initial velocity v_0 decays with $\tau_v = m/\gamma$

Then...

$$D = \langle v_0^2 \rangle \int_0^t ds e^{-\frac{\gamma}{m}s} = \langle v_0^2 \rangle \frac{m}{\gamma} \left(1 - e^{-\frac{\gamma}{m}t} \right)$$

"Diffusion" is constant only at $t \gg m/\gamma$, then

$$D = \langle v_0^2 \rangle \frac{m}{\gamma} = \frac{k_B T}{\gamma}$$

But $\langle \frac{mv^2}{2} \rangle = \frac{1}{2} k_B T$

This is called Green-Kubo formula

$$D = \int_0^{\infty} \langle v(t)v(0) \rangle dt$$

Multiple variables in O-U proc.

$$dx_i = -\Theta_{ik} x_k dt + G_{ik} dW_k$$

(or equivalently $\frac{d}{dt} x_i = -\Theta_{ik} x_k + G_{ik} \sum_k \dot{W}_k$)

Don't need to be symmetric

Just like we did in 1D diffusion,
 solve this SDE set via
 Green's function:

$$X_i(t) = \int_0^t e^{-\Theta_{ik}(t-s)} \Theta_{kl} \xi_l(s) ds$$

initial
 $\xi_l(s)$

$-\Theta_{ik}(t-s)$

Check by differentiation!

Consider a correlation function

$$M_{ik} = X_i(t) X_k(t) \cdot \langle \xi_b(s_1) \xi_g(s_2) \rangle$$

$$M_{ik} = \int_0^t ds_1 \int_0^t ds_2 e^{-\Theta_{ia}(t-s_1)} \Theta_{ab} e^{-\Theta_{kp}(t-s_2)} \Theta_{pg}$$

So we have

$$M_{ik} = \int_0^t ds e^{-\theta_i(t-s)} G_b G_{bp}^T e^{-\theta_p^T(t-s)}$$

(Recall $\int_0^t ds \langle v_i^2 \rangle e^{-\frac{\gamma}{m}t}$)

Call $t-s \rightarrow \tilde{s}$

$$M_{ik} = \int_0^t d\tilde{s} e^{-\theta_i \tilde{s}} G_b G_{bp}^T e^{-\theta_p^T \tilde{s}}$$

take this to ∞

for 1D case: $M = \langle x^2 \rangle = \int_0^\infty dt e^{-2\theta t} \cdot \sigma^2 = \frac{\sigma^2}{2\theta}$

⊙ $m\dot{v} = -\gamma v + A(t)$ $\sqrt{2kT\gamma} \zeta(t)$

$\langle v_i^2 \rangle = \frac{2kT\gamma}{m^2 \cdot 2\gamma/m} = \frac{kT}{m}$ ✓

⊙ $\gamma \dot{x} = -\alpha x + \sqrt{\frac{2kT\gamma}{\alpha}} \zeta(t)$

$\langle x^2 \rangle = \frac{2kT\gamma}{\gamma^2 \cdot 2\alpha/\gamma} = \frac{kT}{\alpha}$ ✓

in potential well

Let us construct

$$\Theta \cdot M + M \cdot \Theta^T$$

$$= \int_0^{\infty} \left(\Theta \cdot e^{-\Theta t} \cdot \Gamma \Gamma^T \cdot e^{-\Theta^T t} + e^{-\Theta t} \cdot \Gamma \Gamma^T \cdot e^{-\Theta^T t} \right) dt$$

this is the full $\frac{d}{dt} (e^{-\Theta t} \Gamma \Gamma^T e^{-\Theta^T t})$

$$= - \int_0^{\infty} dt \frac{d}{dt} (e^{-\Theta t} \Gamma \Gamma^T e^{-\Theta^T t}) = \Gamma \Gamma^T$$

only at lower limit

General (multi-variable) form of Fluctuation - Dissipation relation

$$\Theta_{ik} \langle x_k x_l \rangle + \langle x_i x_k \rangle \Theta_{lk} = \Gamma_{ik} \Gamma_{lk}$$

eq. f.

eq.

ck

lk

il

Lecture 8 ... still on O-U process

It is hard to solve

$$dx = -\theta x dt + \sigma dW$$

(or even comprehend) an SDE...

Instead, it would be better if we had $P(x, t)$

then normal calculus rules

How to systematically derive $P(x, t)$ from the SDE.

Start with Evolution Eq.

$$P(x, t+dt) = \int_{y,t} G(x, t+dt | y, t) P(y, t) dy$$

Normally we think of a propagator $G(x, y)$ with fixed initial y , variable (t, x) .

Here, variable is y ...

To address this, take $\Delta x = x - y$,
 so $y = x - \Delta x$

$$P(x, t + \Delta t) = \int G(x - \Delta x + \Delta x, t + \Delta t) P(x - \Delta x, t) d(-\Delta x)$$

uniform shift:

⊙ G "steps" from $(x - \Delta x)$ into $(x - \Delta x) + \Delta x$:

⊙ We have a uniform function of $(x - \Delta x)$

Taylor expand it:

$$P(x, t + \Delta t) = \int \sum_{n=0}^{\infty} \frac{(-\Delta x)^n}{n!} \frac{\partial^n}{\partial x^n} G(x + \Delta x | x) P(x) d(\Delta x)$$

step Δx

whole range!

Define moments:

$$\langle \Delta x^0 \rangle = 1 \quad : \quad G \text{ normalised for } 0 \rightarrow \infty$$

$$\langle \Delta x^1 \rangle = \int \Delta x G(x + \Delta x | x) d\Delta x \rightarrow -\partial_x \cdot \Delta t$$

$$\langle \Delta x^2 \rangle = \int \Delta x^2 G(x + \Delta x | x) d\Delta x \rightarrow \sigma^2 \Delta t$$

...

$$P(x, t + \Delta t) = P(x, t) - \frac{\partial}{\partial x} (\langle \Delta x \rangle P) + \frac{1}{2} \frac{\partial^2}{\partial x^2} (\langle \Delta x^2 \rangle P) + \dots$$

terms $\sim \Delta t$

+ ...
(no more)

Now substitute moments:

$$\frac{\partial P(x,t)}{\partial t} = \frac{\partial}{\partial x} (\theta x \cdot P(x,t)) + \frac{\sigma^2}{2} \frac{\partial^2}{\partial x^2} P(x,t)$$

for $\theta - \sigma$ process. No more terms $\sim dt$ on r.h.s. (limit $dt \rightarrow 0$)

external force

diffusion constant

$$D = \frac{1}{2} \sigma^2$$

is was an example of using
"Kramers-Moyal equation"

Evolution \rightarrow Expand kernel
in powers of "step"

identify moments

in the PDE for $P(x,t)$

Kramers - Moyal Expansion (general)

Evolution

$$P(x, t+\Delta t) = \int G(x, t+\Delta t | y, t) P(y, t) dy$$

or it could be Kolmogorov - Chapman
if we care about the initial condition:

$$P(x, t+\Delta t | x_0, t_0) = \int G(x, t+\Delta t | y, t) P(y, t | x_0, t_0) dy$$

Again: $\Delta x = x - y$, so $y = x - \Delta x$

ep

shifted
argument

Then we have:

$$\frac{\partial P(x,t)}{\partial t} = \sum_{n=1}^{\infty} (-1)^n \frac{\partial^2}{\partial x^n} \left[D_{(x)}^{(n)} P(x,t) \right]$$

for \forall SDE, not necessarily Wiener, or

$$\frac{\partial P}{\partial t} = \hat{L}_{KM} P(x,t)$$

\hat{L}_{KM} operator

$D_{(x)}^{(n)}$ carry all information about the nature of stochastic proc.

(for Wiener process, there are only two non-zero K-M coeffs)

Practice:

①

$$\dot{v} = -\frac{\gamma}{m} v + \frac{\sqrt{2kT\gamma}}{m} \xi(t)$$

$$dv = -\frac{\gamma}{m} v dt + \frac{\sqrt{2kT\gamma}}{m} dW$$

standard O-U format

$$\langle dv \rangle = -\frac{\gamma}{m} v dt$$

$$\langle dv^2 \rangle = \frac{2kT\gamma}{m^2} \langle dW^2 \rangle \stackrel{dt}{\rightarrow}$$

then:

$$\frac{\partial P(v,t)}{\partial t} = \frac{\gamma}{m} \frac{\partial}{\partial v} (v \cdot P) + \frac{2kT\gamma}{2m^2} \frac{\partial^2 P}{\partial v^2}$$

This equation describes relaxation of $P(v,t)$ towards the equilibrium Maxwell distribution

test the steady state (eq.):

$$0 = \frac{\partial}{\partial v} \left[\frac{\gamma}{m} v \cdot P + \frac{kT\gamma}{m^2} \frac{\partial P}{\partial v} \right]$$

$$\frac{\partial P}{\partial v} = - \frac{m^2}{kT\gamma} \left(\frac{\gamma}{m} v \cdot P \right)$$

$$\frac{dP}{P} = - \frac{m}{kT} v dv$$

mostat equil. $P_e = \text{norm} \cdot e^{-\frac{mv^2}{2kT}}$

2 Relaxation to a fixed equilibrium (in a harmonic potential $V(x)$)

overdamped limit

$$\gamma \dot{x} = -\theta(x-x_0) + \sqrt{2kT\gamma} \cdot \xi(t)$$

will test later

$$dx = -\frac{\theta}{\gamma}(x-x_0) + \frac{\sqrt{2kT}}{\gamma} dW$$

standard O-U format

$$\frac{\partial P(x,t)}{\partial t} = \frac{\partial}{\partial x} \left[\frac{\theta}{\gamma}(x-x_0) P \right] + \frac{2kT}{\gamma} \frac{\partial^2 P}{\partial x^2}$$

Smolucows - equation:
(diffusion with external force)

test: steady state: $\frac{dP}{dx} = -\frac{\theta}{kT}(x-x_0)P : P = P_0 e^{-\frac{\theta(x-x_0)^2}{2kT}}$

i.e. Boltzmann distr.

3 GBM $ds = \mu s dt + \sigma s dw$

$\langle ds \rangle = \mu s dt$

$\langle ds^2 \rangle = \sigma^2 s^2 \langle dw^2 \rangle = dt$

$$\frac{\partial P(s,t)}{\partial t} = -\frac{\partial}{\partial s} (\mu s P(s,t)) + \frac{\sigma^2}{2} \frac{\partial^2}{\partial s^2} (s^2 P)$$

4 Multi-variable process.

(see the last lecture for 'matrix notation')

Brownian motion with force

$m\dot{v} = -\gamma v - \theta(x-x_0) + \sqrt{2kT\gamma} \xi(t)$
 $\dot{x} = v$

$v(x)$
 $x(x)$

linear drift terms.

O-U process

Matrices:

$$\underline{\underline{A}} = \begin{pmatrix} \frac{\gamma}{m} & \frac{\theta}{m} \\ -1 & 0 \end{pmatrix}; \underline{\underline{G}} = \begin{pmatrix} \sqrt{2kT\gamma} & 0 \\ 0 & 0 \end{pmatrix}$$

let us work out the PDE
 $P(v, x, t) \dots$

$$\frac{\partial P}{\partial t} = \frac{\partial}{\partial x_i} \left(\theta_{ik} x_k \cdot P \right) + \frac{1}{2} (GG^T)_{ik} \frac{\partial^2 P}{\partial x_i \partial x_k}$$

$$= \frac{\partial}{\partial v} \frac{\gamma}{m} v \cdot P + \frac{\partial}{\partial v} \frac{\theta}{m} (x - x_0) P$$

$$- \frac{\partial}{\partial x} v P + \frac{2kT\gamma}{m^2} \frac{\partial^2 P}{\partial v^2}$$

full force

$$\frac{\partial P(v, x, t)}{\partial t} + \frac{\partial}{\partial x} (v \cdot P) = \frac{\partial}{\partial v} \frac{\gamma v + \theta (x - x_0)}{m} P$$

$$\text{convective derivative} + \frac{kT\gamma}{m^2} \frac{\partial^2 P}{\partial v^2}$$

general Fokker-Planck equation
Brownian motion in pot.

Lecture 9

In the last lecture ...

Chain rule:

$$\frac{df(x,t)}{dt} = \frac{\partial f}{\partial t} + \frac{\partial f}{\partial x} \frac{\partial x}{\partial t}$$

$$\Rightarrow \dot{f} + (\underline{v}, \underline{\nabla}) f$$

(or is it convective derivative $\underline{\nabla}(\underline{v} \cdot \underline{f})$?)

In K-M expansion:

$$\frac{\partial^n}{\partial x^n} \int (\Delta x)^n G(x + \Delta x/x) P(x,t) d\Delta x$$

$$\Rightarrow \frac{\partial^n}{\partial x^n} \left(\mathcal{D}^{(n)}(x) P(x,t) \right)$$

(definitely under $\frac{\partial}{\partial x}$)

We have seen the Smoluchowski equation in harmonic potential (for O-U process)

What if the force $f(x)$ is arbitrary: $f = -\frac{\partial V}{\partial x}(x)$

SDE

(overdamped limit) $\gamma \dot{x} = f(x) + \sqrt{2kT\gamma} \xi(t)$

will derive soon...

via K.-M. expansion:

$$(*) \quad \frac{\partial P(x,t)}{\partial t} = -\frac{\partial}{\partial x} \left(\frac{f(x)}{\gamma} P(x,t) \right) + \frac{1}{2} \frac{2kT\gamma}{\gamma^2} P''$$

diffusion in γ force.

$$= -\frac{\partial}{\partial x} \left(\frac{f(x)}{\gamma} P \right) + \frac{kT}{\gamma} \frac{\partial^2 P}{\partial x^2}$$

$$D = \frac{kT}{\gamma} \equiv \frac{1}{2} \sigma^2$$

Write it in an alternative equivalent form:

$$\frac{\partial P}{\partial t} = -\nabla J(x,t)$$

in multi-dimensions: $\text{div } \underline{J}$

where the

"flux" or

"current of probability"

$$\underline{J} = -D \frac{\partial P}{\partial x} + \frac{f(x)}{\gamma} P(x,t)$$

"Fick's Law"

Another equivalent form: $D = \frac{kT}{\gamma}$

$$J(x,t) = -D e^{-\beta V(x)} \frac{\partial}{\partial x} \left[e^{\beta V(x)} P(x,t) \right]$$

In all cases, we see a general "flux" $\underline{J} = \rho \underline{v}$, and

Continuity equation: $\dot{P} = -\text{div } \underline{J}$
for conserved field $\int P dx = 1$

What if we have an x -dependent noise: $G(x)$?

$$dx = \mu(x,t) dt + \underline{G}(x,t) dW$$

Then we "probably" would still have following Ito's maths!

$$\frac{\partial P(x,t)}{\partial t} = -\frac{\partial}{\partial x} (\mu(x,t) P) + \frac{1}{2} \frac{\partial^2}{\partial x^2} (G^2(x,t) P)$$

from K.M. expansion.

However we shall see that ~~the~~

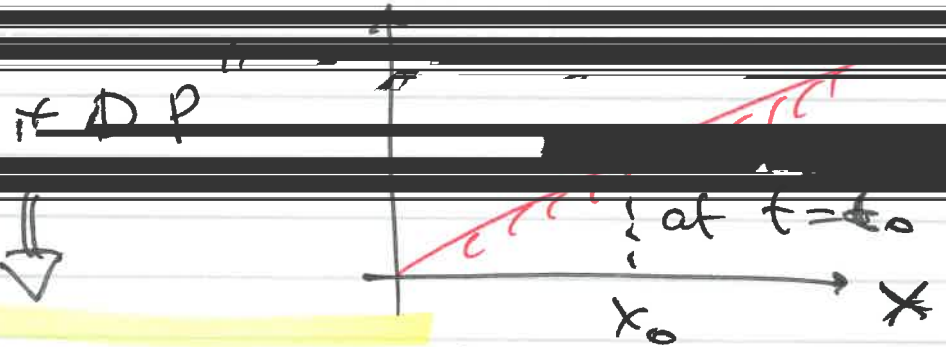
phys.

To finish the O-U section:

two examples:

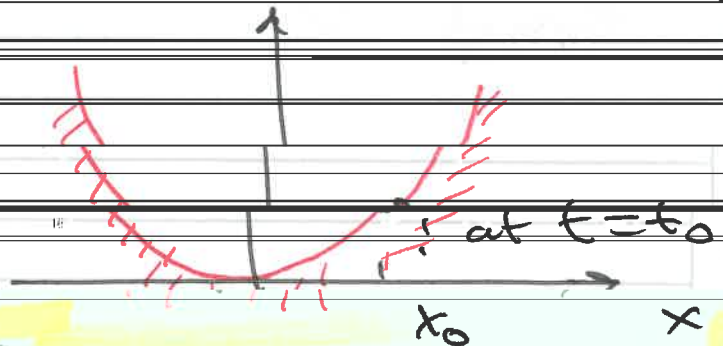
1) Diffusion in constant force

e.g. sedimentation under gravity



$$P(x,t) = \frac{1}{\sqrt{4\pi D(t-t_0)}} \exp\left[-\frac{(x-x_0 + \frac{f}{\gamma}(t-t_0))^2}{4D(t-t_0)}\right]$$

at t = t₀ the ...



$$P(x,t) = \frac{1}{\sqrt{2\pi kT S(t)/\alpha}} \exp\left[-\frac{\alpha}{2} \frac{(x-x_0 e^{-\frac{\alpha}{\gamma}(t-t_0)})^2}{kT S(t)}\right]$$

with $S(t) = 1 - e^{-\frac{2\alpha}{\gamma}(t-t_0)}$

Convection Diffusion

Then

$d f$

$f + h$

e is a background flow with velocity u , diffusion on top

Recall $\frac{\partial P(x,t)}{\partial t} = D \nabla^2 P$

Now, when $u(x)$ is present: extra flux $u \cdot P$

$$\frac{\partial P}{\partial t} = D \nabla^2 (e^{-\beta V} \nabla [e^{\beta V} \cdot P]) - \nabla (u \cdot P)$$

Or re-write:

$$\frac{\partial P}{\partial t} + \nabla (u(x) \cdot P) = \text{"old r.h.s."}$$

if $\text{div } u = 0$

$$= -\frac{\partial}{\partial x} \left(\frac{f(x)}{\gamma} P \right) + D \frac{\partial^2 P}{\partial x^2}$$

convective derivative

r.h.s. of Smoluchowski

$$\frac{\partial P}{\partial t} + (u \cdot \nabla) P = \dots$$

Many implications, since $u(x)$ adds to the potential $V(x)$

$$\frac{\partial P}{\partial t} = -\nabla \cdot (f(x) + u(x)) P + D \frac{\partial^2 P}{\partial x^2}$$

New structure emerging.

What if $u = \text{const}$:

$$\frac{\partial P}{\partial t} + u \frac{\partial P}{\partial x} = D \frac{\partial^2 P}{\partial x^2}$$

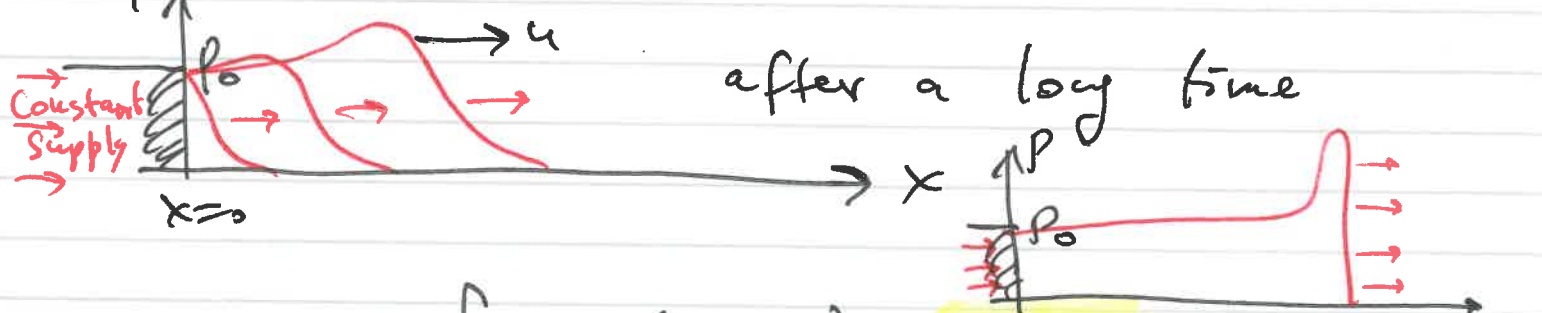
Similar to diffusion under constant force.

So if $t=0$ $P = \delta(x)$

$$P(x,t) = \frac{1}{\sqrt{4\pi Dt}} e^{-\frac{(x-ut)^2}{4Dt}}$$

easy!

But if $x=0$ $P=P_0$ (Boundary Condition)



$$P(x,t) = \frac{1}{2} P_0 \left[\text{Erfc} \left(\frac{x-ut}{\sqrt{4Dt}} \right) + e^{\frac{u \cdot x}{D}} \text{Erfc} \left(\frac{x-ut}{\sqrt{4Dt}} \right) \right]$$

"Dispersivity" parameter

Lecture 10

Mean

(MFPT)

First Passage
Time.

Examples Class #1 at 2pm
today — Here.



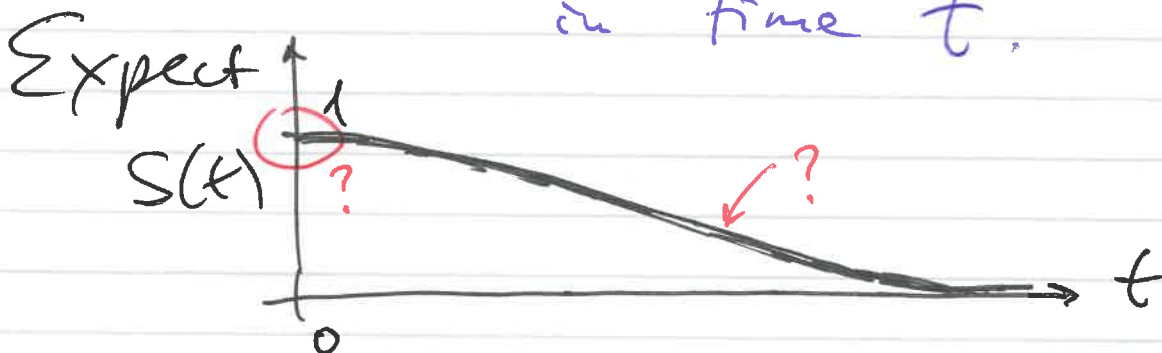
⊙ What is the probability of escape in time t ?

⊙ Mean time of escape?

(For \forall stochastic process)

Approach #1: via survival probability

$S(t)$ that it did not escape in time t .



If we knew the full process probability $P(x, t)$, then

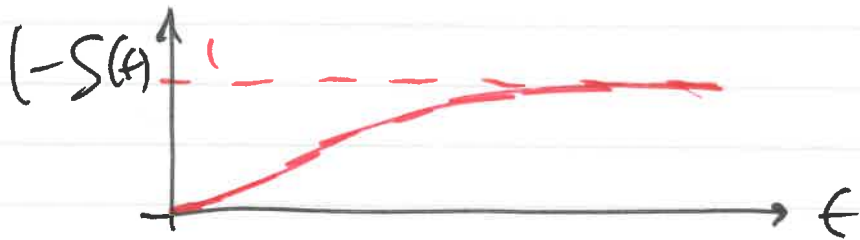
$$S(t) = \int_{\text{all values } x} P(x, t) dx$$

Non-equilibrium process.

$$\int P(x, t) dx = 1$$

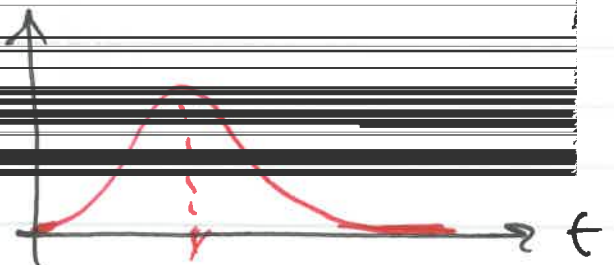
if normalised

Then $(-S(t))$ is the probability to have escaped in time t .



Consider a small step Δt :

$$S(t) - S(t + \Delta t) : \text{Number of escaped particles}$$

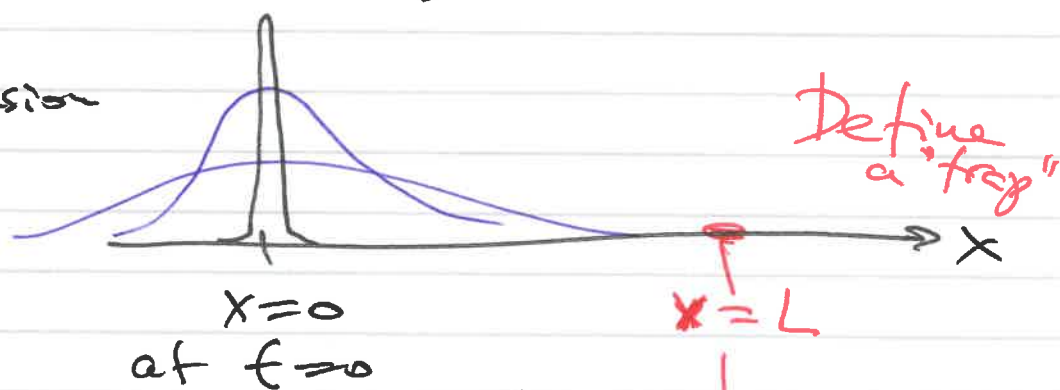


then $\langle t \rangle = \int_0^{\infty} t f(t) dt$
 average time to escape (by parts...)

$$\langle t \rangle = \int S(t) dt$$

Let's test a simple example

1D diffusion

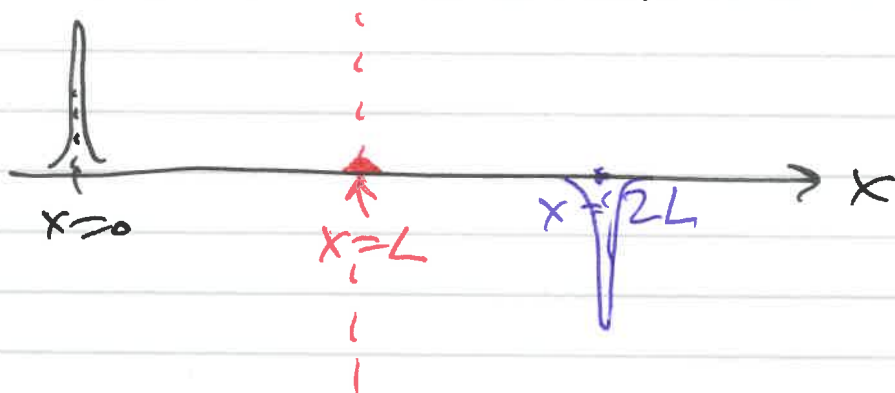


$$P(x,t) = \frac{1}{\sqrt{4\pi Dt}} e^{-\frac{x^2}{4Dt}}$$

Absorbing Boundary Condition
 $P(L,t) = 0$

We must find the correct $P(x,t)$ satisfying this B.C.

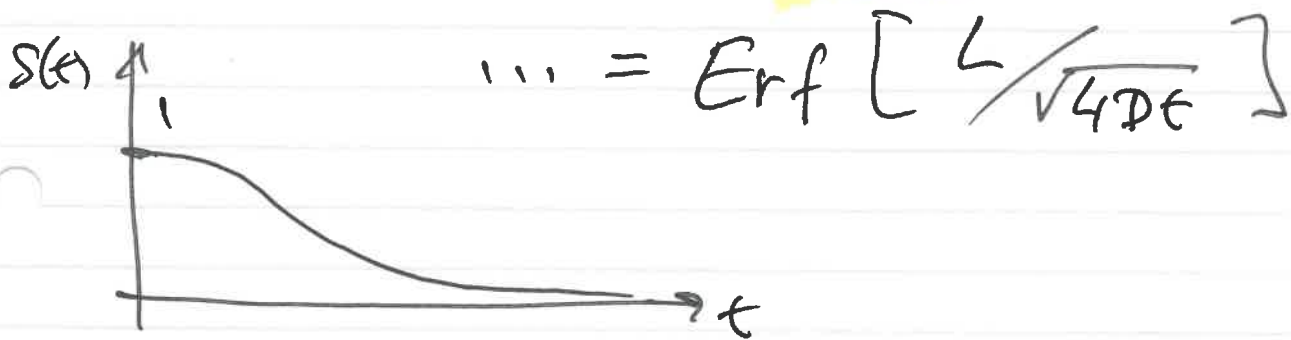
Here we can use Method of Images!



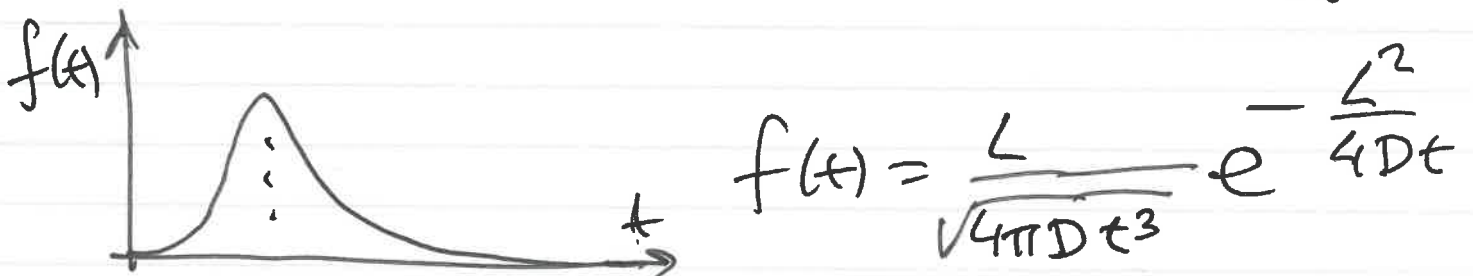
Find $P(x,t) = \frac{1}{\sqrt{4Dt}} \left(e^{-\frac{x^2}{4Dt}} - e^{-\frac{(x-2L)^2}{4Dt}} \right)$

Then $S(t) = \int_{-\infty}^L P(x,t) dx$

All available space!



Then we find $f(t) = -\frac{\partial S}{\partial t}$

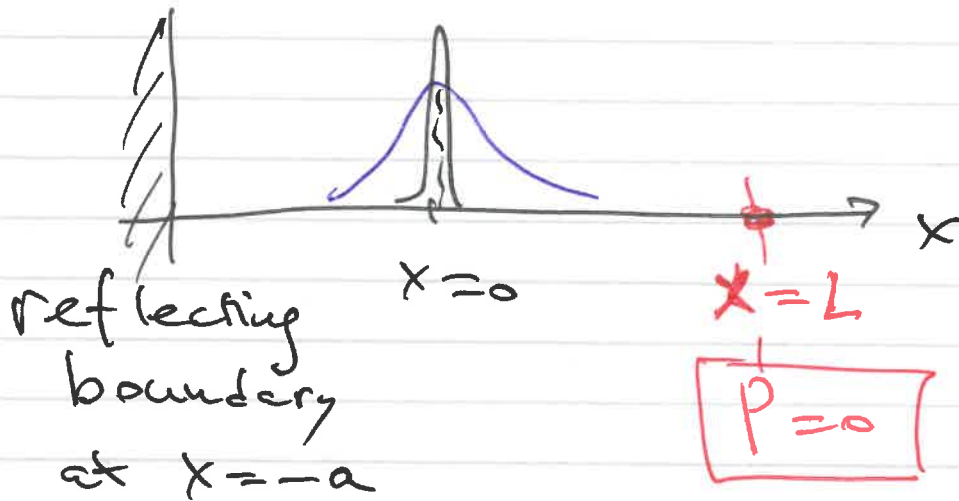


MFPT = $\langle t \rangle = \int_0^{\infty} t \frac{L}{\sqrt{4\pi Dt^3}} e^{-\frac{L^2}{4Dt}} dt$

$\sim \int_0^{\infty} \frac{1}{\sqrt{t}} dt \rightarrow \infty$ ✓

This is not a well-posed problem
(∞ time of travel to
 $x \rightarrow -\infty$ and back)

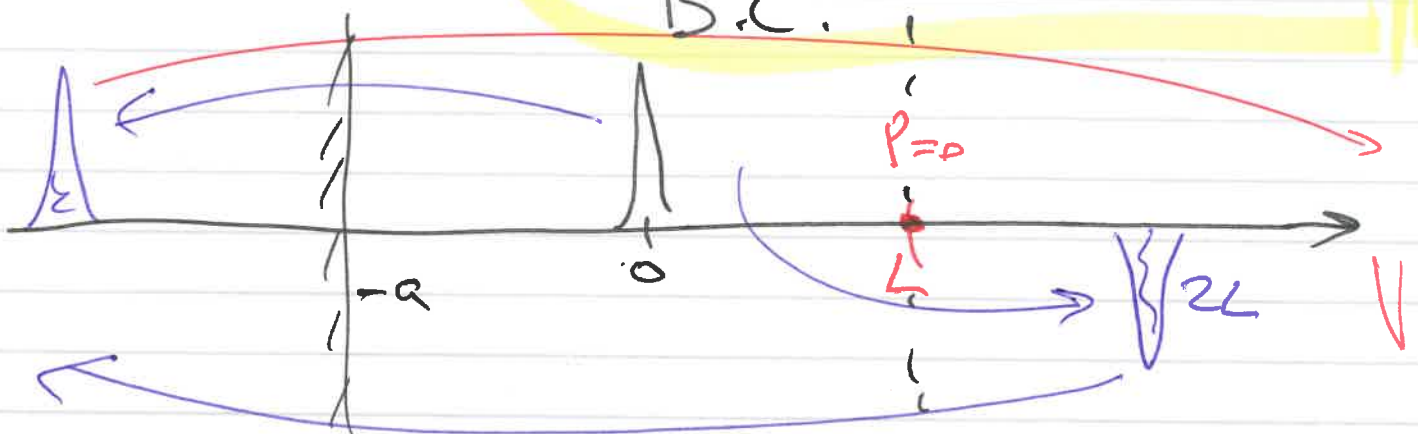
Make it well-posed:



i.e. $\frac{\partial P}{\partial x} = 0$

How to find $P(x,t)$ that satisfies both

B.C.



Build an ∞ series of \pm images reflecting $e^{-\frac{x^2}{4Dt}}$

OR...

Just solve the diffusion equation $\dot{P} = DP''$ with these two B.C.

$\rightarrow \infty$ series of $\sum_n \delta_{in} \left(\frac{n\pi x}{L+a} \right) e^{-\tau D t}$

...

Once $P(x,t)$ is found

$$\rightarrow S(t) = \int_{-a}^L P(x,t) dx$$



$-a$ All available space

$$MFPT = \frac{L(L+2a)}{2D} \quad \text{for start at } x=0$$

if $a=0$ $MFPT = L^2/2D$

} Diffusion time (mean) over L

But if the initial condition is an arbitrary $x=x_0$ (at $t=0$),

then MFPT is a function of x_0 . (e.g. if $x_0=L$ $MFPT=0$)

Now a different approach to MFPT, for Wiener process.

#2: Via Adjoint Fokker-Planck operator

We saw the Smoluchowski equation
(a case of Fokker-Planck equation set)

$$\frac{\partial P(x,t)}{\partial t} = -\frac{\partial}{\partial x} \left(\frac{f(x)}{\gamma} P \right) + D \frac{\partial^2 P}{\partial x^2}$$

$$\left(\text{or } -\frac{\partial}{\partial x} (\mu(x,t) P) + \frac{\sigma^2}{2} \frac{\partial^2 P}{\partial x^2} \right)$$

Define a Fokker-Planck operator acting on X .

$$\frac{\partial P}{\partial t} = -\hat{L}_{FP} P(x,t)$$

We saw the alternative form of it:

$$\hat{L}_X = D \frac{\partial}{\partial x} \left(e^{-\beta V(x)} \frac{\partial}{\partial x} \left[e^{\beta V(x)} P(x,t) \right] \right)$$

this operator acts on X !

$$P(x,t) = e^{-\hat{L}_X t} P(x,0)$$

If we want MFPT:

$$\text{MFPT} = \int_0^{\infty} S(t) dt$$

$$= \int_0^{\infty} dt \int dx P(x,t | x_0, 0)$$

(vd.)

initial condition

$$\equiv \tau(x_0)$$

Could we find an equation that would return $\tau(x_0)$?

To find that, we need operators that act on the initial condition

(that's not what we are used to)

Need Kolmogorov-Chapman

$$P(x,t | x_0, 0) = \int G(x,t | y, t') P(y, t' | x_0, 0) dy$$

here

Since $\frac{\partial P}{\partial t} = - \hat{L} P$

Acting on x

Let me differentiate ar.r.t. t' ^{Kolmogorov-Chapman}

$$\frac{\partial}{\partial t'} P(x, t | x_0, 0) \equiv 0$$

$$0 = \int G(x, t | y, t') \frac{\partial P(y, t' | x_0, 0)}{\partial t'} + P(y, t' | x_0, 0) \frac{\partial G(x, t | y, t')}{\partial t'} dy$$
$$= \int G(x, t | y, t') \cdot \left[-\hat{L}_y P(y, t' | x_0, 0) \right]$$

Continue next ...
deal with this...

Adjoint Fokker-Planck Derivation of MFPT

Patrick Collins <pac74@cam.ac.uk>

Tue 4/2/2024 5:16 PM

To: Eugene Terentjev <emt1000@cam.ac.uk>

Cc: Vivian Perez <oap22@cam.ac.uk>

1 attachments (2 MB)

Adjoint FP MFPT derivation.docx

Dear Professor Terentjev,

My colleague and I have been looking over the derivation for the MFPT from the adjoint Fokker-Planck operator. We weren't sure on the origin of the - sign here in your notes:

$$\begin{aligned} \hat{L}_x^+ \tau(x_0) &= \int_0^\infty dt \int dx \frac{\partial}{\partial t} P(x, t | x_0, 0) \\ &= + \int d\tilde{\epsilon} \frac{\partial}{\partial \tilde{\epsilon}} \underbrace{\int P dx}_{S(\tilde{\epsilon})} \\ &= - \int f(\tilde{\epsilon}) d\tilde{\epsilon} = -1 \end{aligned}$$

Annotations in the image: $\tilde{\epsilon} = t - t_0$, $d\tilde{\epsilon} = -dt_0$. A red box highlights the final result $\hat{L}_x^+ \tau(x_0) = -1$ with the note "New result".

We have worked through this and believe it should be +1. Furthermore, the definition of the adjoint Fokker-Planck operator earlier in the notes seems to miss a - sign, which corrects for the - previously.

gives $\hat{L}_x^+ = -\mu(x) \frac{\partial}{\partial x} - D \frac{\partial^2}{\partial x^2}$

So that if $\hat{L}_x = D e^{-\beta V(x)} \frac{\partial}{\partial x} \left(e^{\beta V(x)} \frac{\partial}{\partial x} \right)$

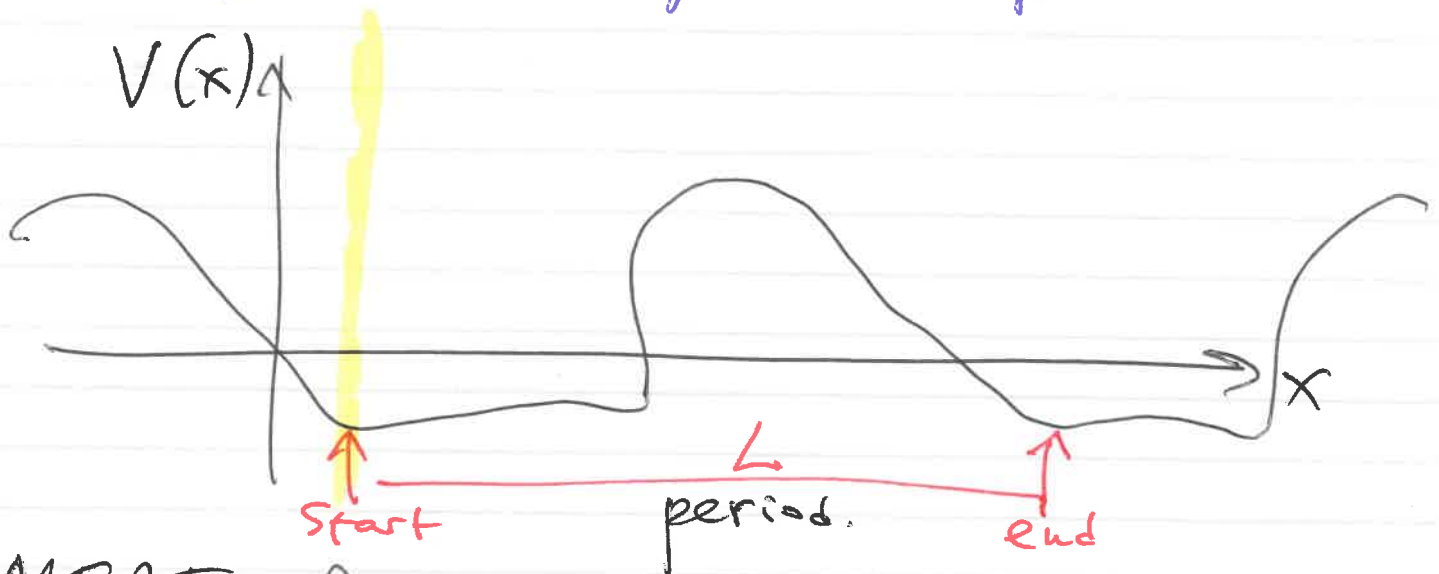
Then $\hat{L}_x^+ = D e^{\beta V(x)} \frac{\partial}{\partial x} \left(e^{-\beta V(x)} \frac{\partial}{\partial x} \right)$

check by direct differentiation

We believe that combining these two corrections leads to the correct result. We have attached the workings in a word document to these email, please let us know if you would like us to rewrite them in a neater format. Do you think our approach to this is correct?

Lecture 12 - finishing MFPT ...

⊙ Diffusion in periodic potential



MFPT from "start" to "end"

$$\tau = \frac{1}{D} \int_{\text{start}}^L dx e^{\beta V(x)} \int_0^x e^{-\beta V(y)} dy$$

⊙ start
⊙ left boundary

Define "effective diffusion" in time τ :

$$L^2 = 2 D_{\text{eff}} \tau,$$

So $D_{\text{eff}} = \frac{L^2}{2\tau} = \frac{D}{\int_0^L e^{\beta V(x)} dx \int_0^x e^{-\beta V(y)} dy}$

Always big ...

Any potential:

$$D_{\text{eff}} \ll D$$

What we did in MFPT was strictly 1D...

In higher-dimensions, the issue arises!



x

ϵ ,
boundary

Abs.
region

miss!

!

MFPT must depend on the size target

Examples

① "Form: a fit"

→ Szabo et al. 1980



size ϵ

② "Narrow escape"

→ Holcman et al. 2000

size ϵ

How long it takes to make contact?

$$\text{MFPT: } 1D \quad \tau \sim \frac{L^2}{D}$$

$$2D \quad \tau \sim \frac{L^2}{D} \ln(1/\epsilon)$$

$$3D \quad \tau \sim \frac{L^3}{D\epsilon}$$

Last topic

"Multiplicative Noise"

i.e., $dx = \mu(x,t) dt + \sigma(x) dW$
(E.g. in GBM)

Corresponding F-P equation

$$\frac{\partial P(x,t)}{\partial t} = - \frac{\partial}{\partial x} (\mu(x,t) \cdot P) + \frac{1}{2} \frac{\partial^2}{\partial x^2} (\sigma^2(x) P)$$

or is it $\frac{1}{2} \sigma^2(x) \frac{\partial^2 P}{\partial x^2}$ ^{2nd Kramers - Moyal cf.}

or is it $\frac{1}{2} \sigma(x) \frac{\partial}{\partial x} \left(\sigma(x) \frac{\partial P}{\partial x} \right)$

or something else

Let's re-examine the Kramers - Moyal process: evaluate $\langle \Delta x^n \rangle$

$$\langle \Delta x \rangle = \int (\mu + \frac{1}{2} \sigma^2) ds$$

Average in another way: time average

$$= \mu(x,t) \Delta t + \sigma(x[t]) \int \xi(s) ds$$

Wiener ...

No need to derive it

to [Ito]

Mathematically consistent (Ito)

○ version is: evaluate at t ,
(start of interval)

$$\phi(x[t]) \int_t^{t+\Delta t} dW$$

Statistically independent!

○ Stratonovich version:
evaluate at the middle

$$\int \phi(x[t + \frac{1}{2}\Delta t]) \zeta(t) dt$$

○ More recently: evaluate at an arbitrary point

and compare with experiment

$$\phi(x[t + \alpha \Delta t])$$

Ito: $\alpha = 0$

Stratonovich: $\alpha = \frac{1}{2}$

Lau-Lubensky: $\alpha = 1$ (end of ...)

If we follow Ito process:

$\alpha=0$

$$\frac{\partial P}{\partial t} = -\frac{\partial}{\partial x}(\mu P) + \frac{1}{2} \frac{\partial^2}{\partial x^2} (\sigma^2(x) P)$$

If we follow Stratonovich process:

$\alpha=1/2$

$$\frac{\partial P}{\partial t} = \frac{1}{2} \frac{\partial}{\partial x} \left(\sigma^2(x) \frac{\partial}{\partial x} [\sigma^2(x) P] \right)$$

If we follow Law-Lubensky:

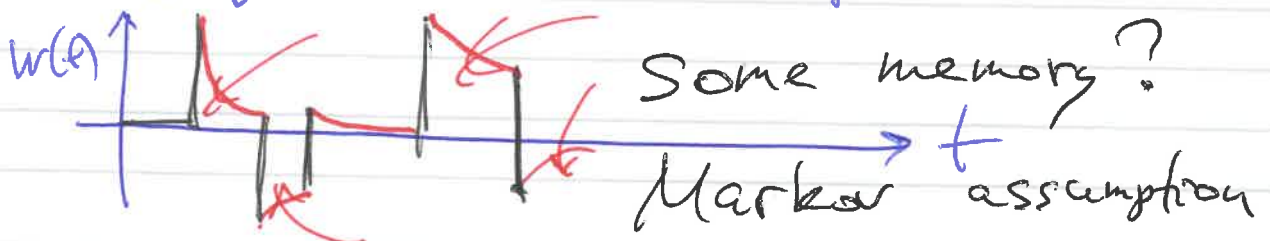
$\alpha=1$

$$\frac{\partial P}{\partial t} = \frac{1}{2} \frac{\partial}{\partial x} \left(\sigma^2(x) \frac{\partial P}{\partial x} \right)$$



The formal accepted resolution of this is via a more careful look at the approximation leading to the Wiener process ...

Physical (e.g. thermal noise) process



Wong - Zakai Theorem:

applies when a physical process behind the approximate $W(t)$ is a sequence of deterministic events " W_n "

we must modify the SDE

$$dx = \left(\mu(x,t) + \frac{1}{2} \sigma(x) \frac{\partial \sigma}{\partial x} \right) dt + \sigma(x) dW$$

Must have an additive drift term

We then work with proper Ito process (statistically independent) $\sigma(x)$ and dW

$$\begin{aligned} \rightarrow \frac{\partial P(x,t)}{\partial t} &= \underbrace{-\frac{\partial}{\partial x}(\mu \cdot P)}_{\text{1st Kramers-Moyal term}} - \frac{1}{2} \frac{\partial}{\partial x} \left(\sigma \frac{\partial \sigma}{\partial x} \cdot P \right) \\ &+ \underbrace{\frac{1}{2} \frac{\partial^2}{\partial x^2} (\sigma^2 P)}_{\text{2nd Kramers-Moyal}} \end{aligned}$$

Simple algebra gives:

$$\frac{\partial P(x,t)}{\partial t} = -\frac{\partial}{\partial x} (\mu(x)P) + \frac{1}{2} \frac{\partial}{\partial x} \left[\zeta(x) \frac{\partial}{\partial x} (\zeta(x)P) \right]$$

exactly the
Stratonovich version!

When $\zeta = \text{const}$: $D = \frac{1}{2} \zeta^2$, we had

$$J = -D e^{-\beta V(x)} \frac{\partial}{\partial x} \left(e^{\beta V(x)} P(x,t) \right)$$

Now we have the flux:

$$J = -\frac{1}{2} \zeta(x) e^{-\beta V(x)} \frac{\partial}{\partial x} \left(\zeta(x) e^{\beta V(x)} P \right)$$

As long as we identify the
"friction constant" as

$$\gamma(x) = \frac{2kT}{\zeta^2(x)}$$

a version
of F.D.T.

then $D(x) = \frac{kT}{\gamma(x)} = \frac{1}{2} \zeta^2(x)$ is
still valid.